

Computational Methodologies for the Non-linear Analysis of Concrete and Masonry Structures

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Overview

- Introduction
 - earthquake engineering problems
 - issues in finite element analysis
- Objectives
- Material models
 - combined damage/plasticity model
 - time dependent damage model
- Analysis methods
 - dynamic analysis
 - static analysis
- Applications and conclusions

Earthquake-resistant design of concrete and masonry structures

- Project motivation:
 - contribution to safer building practice in seismic regions
 - increased understanding of failure mechanisms in concrete structures and masonry structures using advanced numerical techniques

Examples of failure in masonry buildings





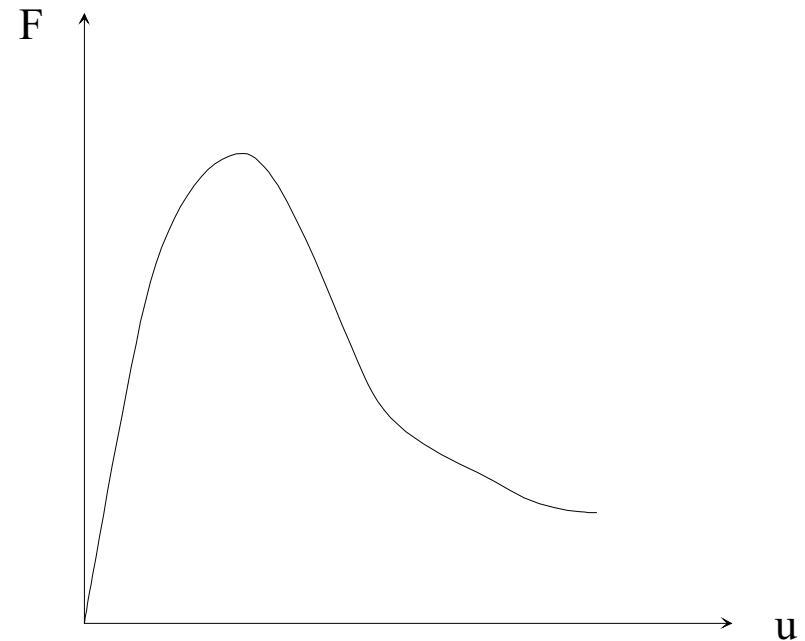


Examples of failure in infilled r.c. structures



Non-linear finite element structural analysis

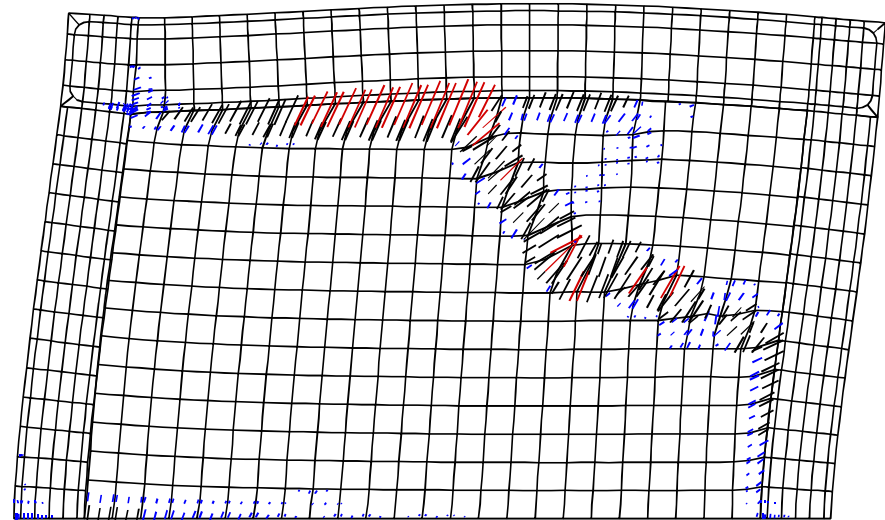
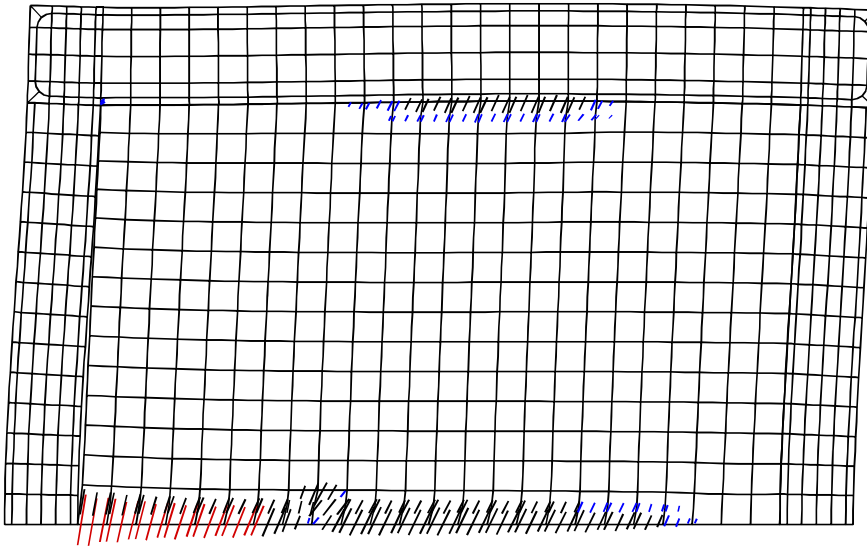
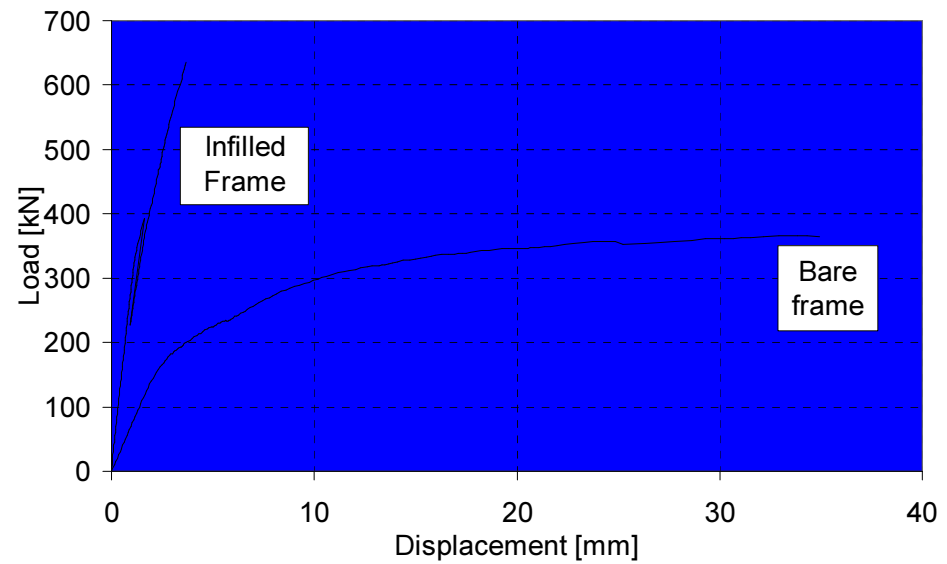
- Used to determine
 - deformation
 - development of damage
 - load displacement diagram



Difficulties related to F.E. analysis

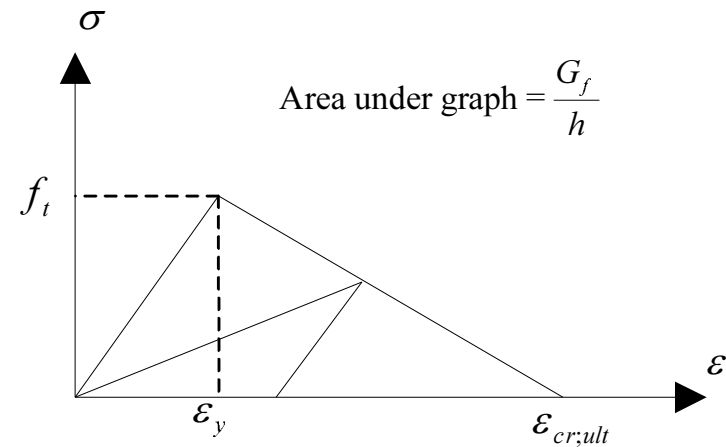
- Correct prediction of structural response is difficult to obtain
 - numerical problems can be encountered especially beyond peak load
- Current non-linear material models are not complete particularly in the case of masonry
 - good agreement can be obtained only after experimental results are known

Analysis of an infilled r.c. frame



Material modelling issues

- brittle material response
- damage can occur in more than one location
- problem is path dependent and solutions are not necessarily unique
- limited insight into material behaviour and limitations in material model formulation can lead to mathematically ill-posed problems



Solution method

- Discretised problem leads to a set of non-linear equations which needs to be solved at each step of the analysis:

$$f : R^n \rightarrow R^n$$

find displacements such that $f = 0$

- System of equations is usually solved using the Newton method or variations thereof

$$J_k s_N = f_k$$

Objectives

- Formulation of material models
 - realistic response in tension, compression etc.
 - better numerical performance
- Formulation of solution methods which avoid the use of Newton iterations

Combined material model: cracking

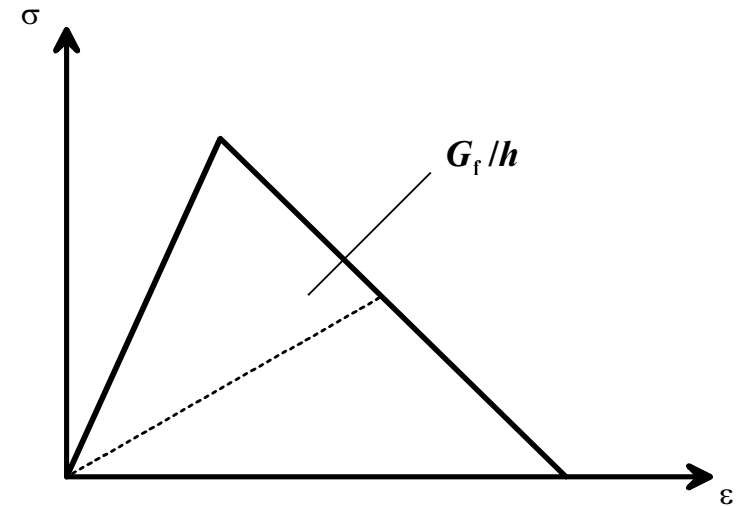
- Isotropic damage model:

$$\alpha = \frac{\sigma}{E} \left(1 - \frac{G_f}{h} \right)$$

- linear softening
- ultimate strain

$$\Pi_{t,u} = \frac{2G_t}{f_t h}$$

- total stress

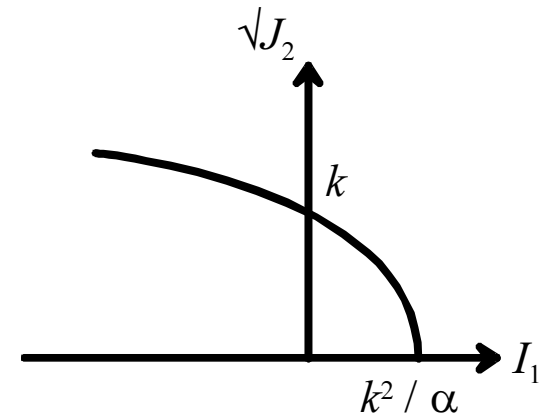


$$\alpha = E \left\{ \frac{\max(\Pi_1, 0)}{\max(\Pi_2, 0)} + \frac{\min(\Pi_1, 0)}{\min(\Pi_2, 0)} \right\}$$

Crushing

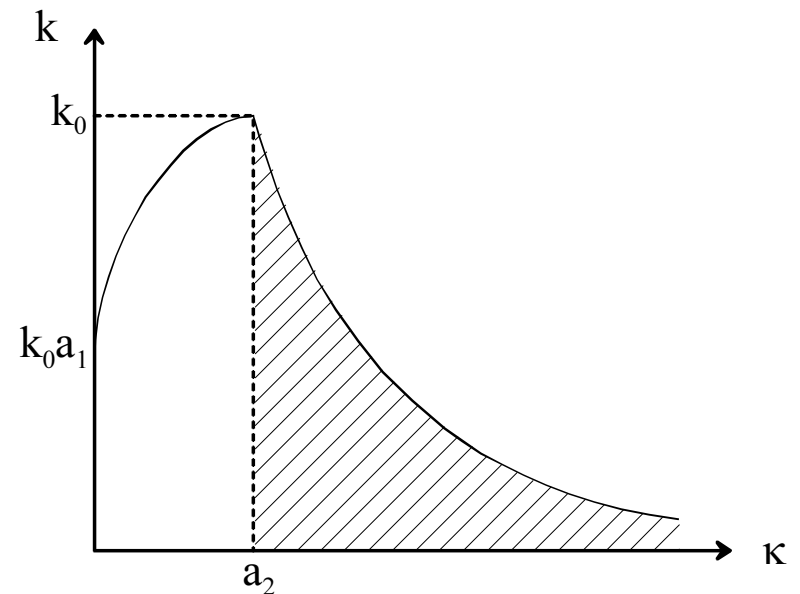
- Quadratic Drucker-Prager model

$$f = \alpha \sqrt{J_2} + \beta I_1 - k^2$$



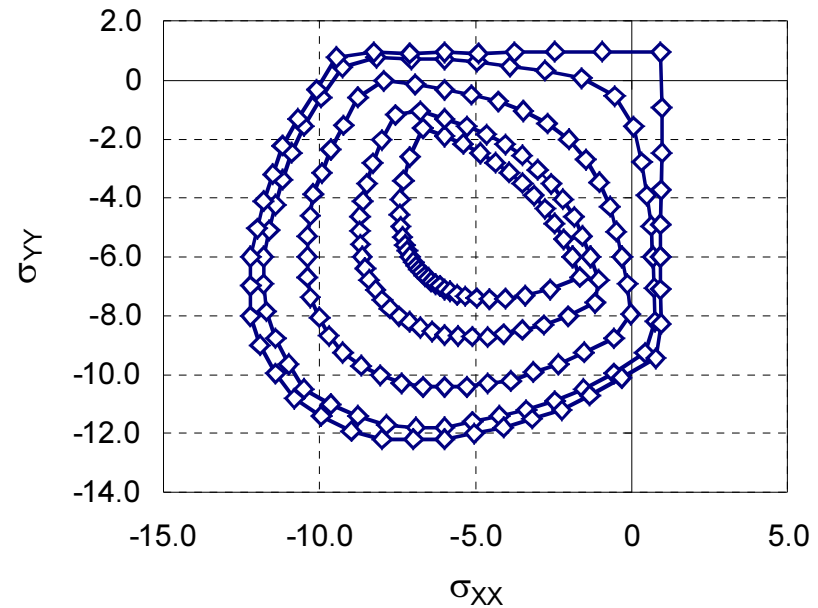
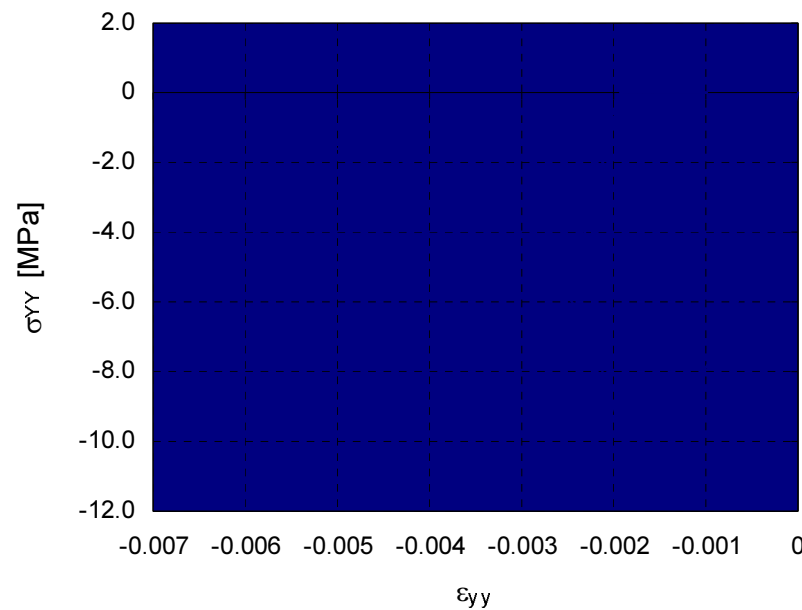
- damage

$$Y = Y_0 + \sqrt{\frac{2}{3}} \frac{A_1 \Gamma}{6 A_1 \Gamma}$$



Combined model response

- material with $f_t=1$ MPa; $f_c=10$ MPa



$\tau=0, 1.5, 3, 4, 5$ MPa

Rate dependent damage model

- Based on the elastic damage model

$$\alpha = \frac{\sigma}{E} \frac{1}{1 - \delta} \quad \text{or} \quad \sigma = E(1 - \delta)\alpha$$

- damage rate law:

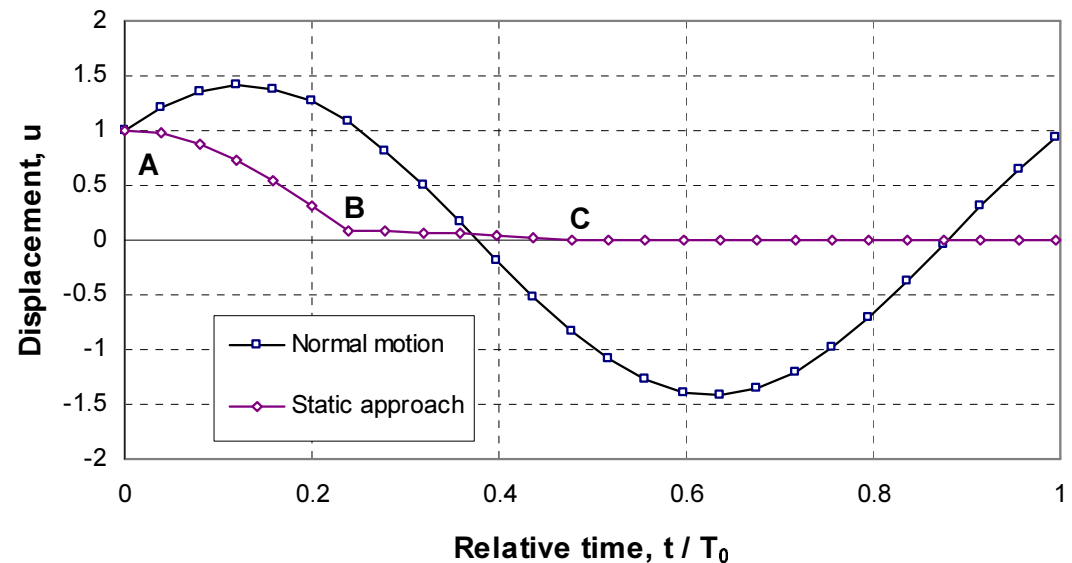
$$\frac{d\delta}{dt} = c \left\langle \frac{\sigma}{\sigma_t} - 1 \right\rangle^a (1 - \delta)^b$$

Solution procedures

- Method which avoid use of Newton iterations
- Dynamic problems
 - predictor-corrector methods for problems described by ordinary differential equations with given initial conditions, e.g. Newmark's method, central difference method (explicit)
- Static problems
 - dynamic relaxation method

Static solution

- Dynamic relaxation: introduces damping to make a transient explicit dynamic analysis converge to the static solution.
- Modified dynamic relaxation method for static analysis:
 - no damping required
 - velocity of system set to zero at moments when the absolute acceleration of the system has reached a minimum

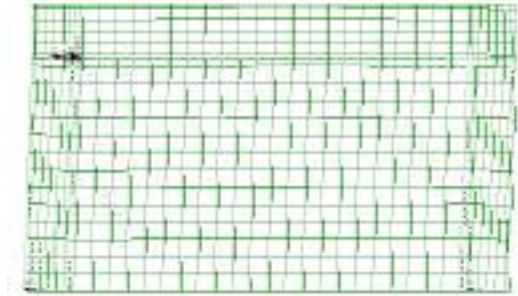


Problems considered

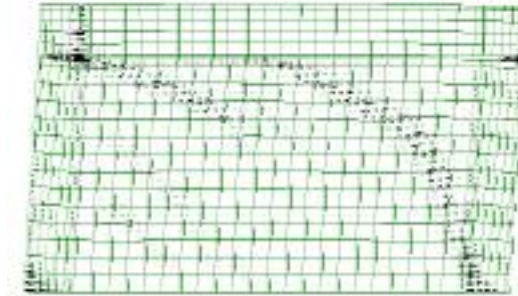
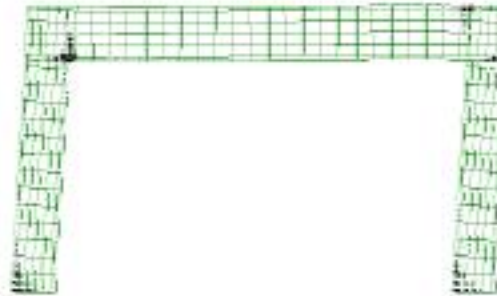
- Bar under tension to study problem of mesh independence
- Masonry panels under
 - tension
 - compression
 - horizontal loading
- Infilled r.c. frames

Deformations (x40) and crack patterns

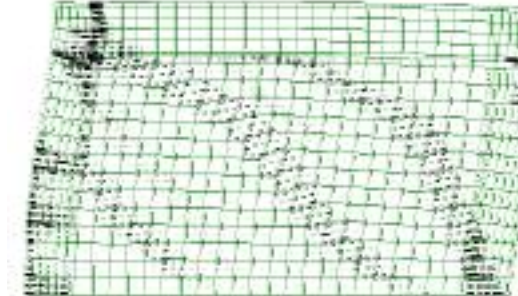
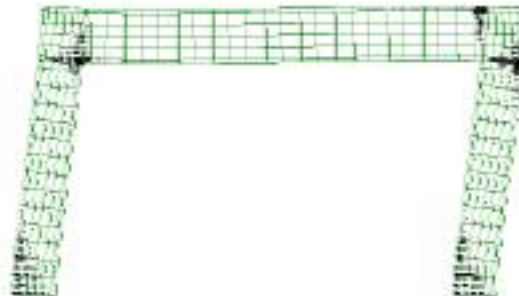
2 mm



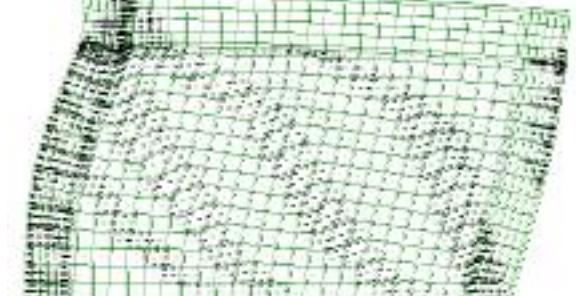
4 mm

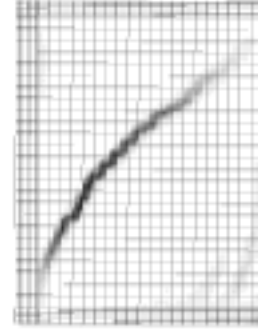


8 mm

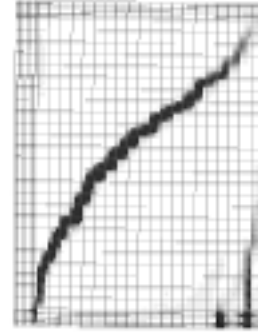


16 mm

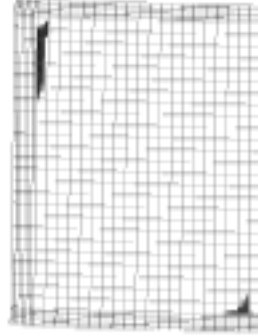




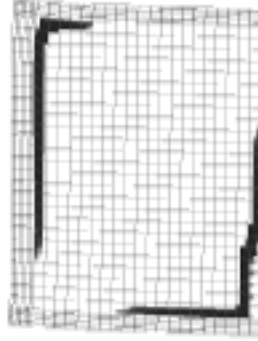
$u=0.0$ mm



$u=1.2$ mm



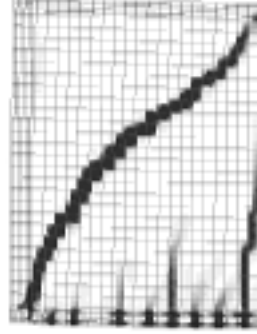
$u=0.14$ mm



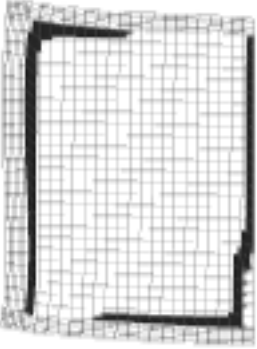
$u=0.20$ mm



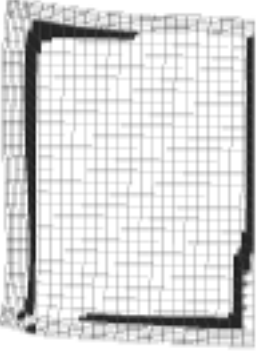
$u=2$ mm



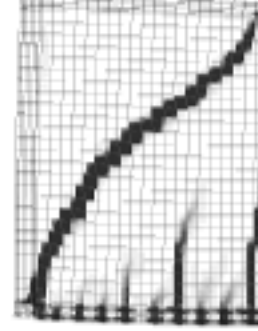
$u=2.4$ mm



$u=0.32$ mm



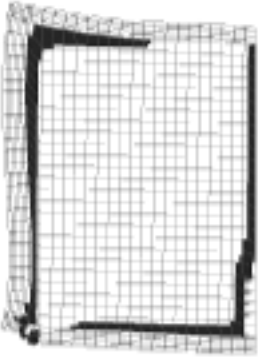
$u=0.38$ mm



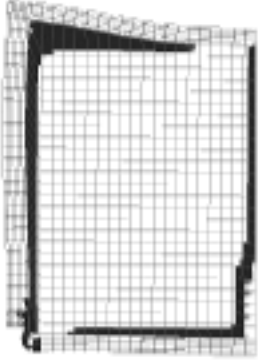
$u=3$ mm



$u=4.5$ mm



$u=0.44$ mm



$u=0.50$ mm

Conclusions

- Explicit dynamic analysis
 - requires no solution of non-linear equations
 - delivers results where other methods fail
 - allows a direct evaluation of material model performance
 - allows a simplification of the programming
- Additional DR type procedure can be used for a static analysis
 - automatic
 - delivers results similar to those obtainable with the Newton method with constant initial stiffness
 - some issues related to convergence speed and accuracy remain

Conclusions, continued

- Material models
 - marked interaction between cracking and crushing failure modes
 - shear behaviour has a great influence on the calculated global response
 - rate dependent model is superior to rate independent model in achieving mesh objective results

Possible future developments

- Solution methods
 - improvement of speed and accuracy
 - adaptive procedures
- Material models
 - comparison with experiments
 - calibration of model parameters
 - introduction of damping