

# Estimation of model parameters in nonlocal damage theories by inverse analysis techniques

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Structural Mechanics*

Nieuwegein, November 9th 2005



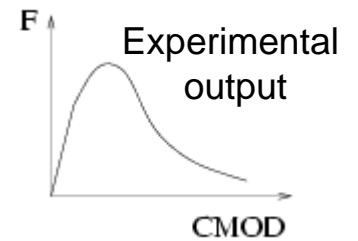
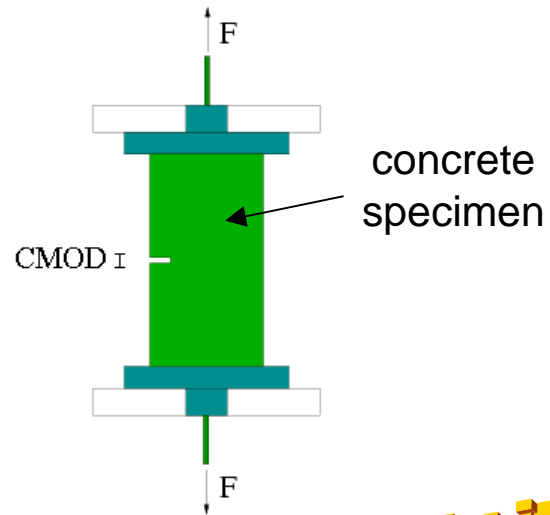
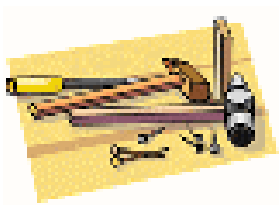
# Outline

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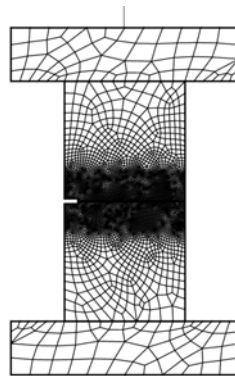
- ☐ Setting the scene
- ☐ Project objectives
- ☐ Forward problem
- ☐ Inverse problem
- ☐ The inverse techniques
- ☐ Experimental data
- ☐ Results
- ☐ Conclusions

# Setting the scene

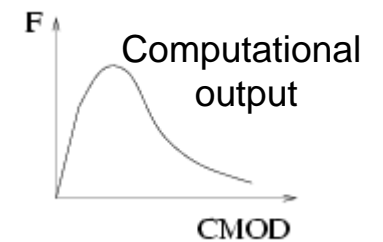
## Experimental world



## Numerical world



mathematical equations  
containing parameters



**limited amount  
of work**



# Setting the scene

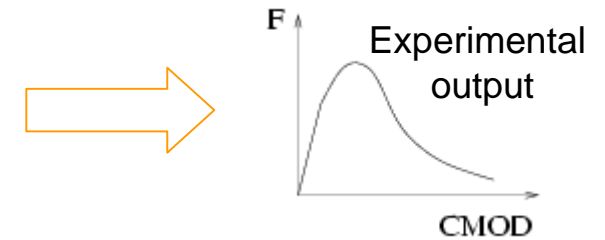
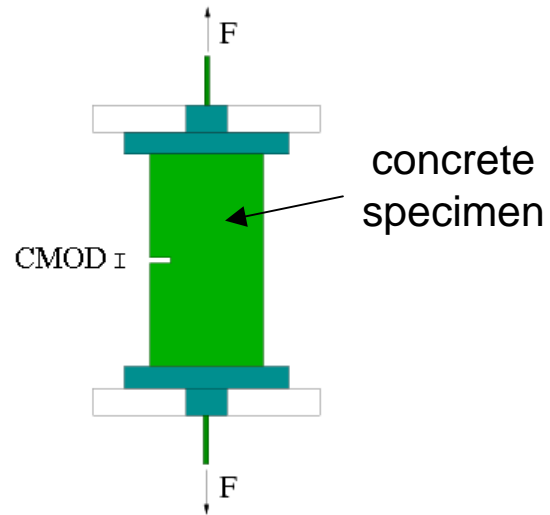
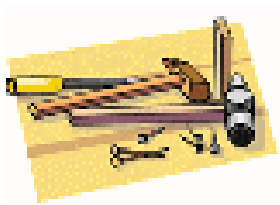
Result:



"Quit moving!"

# Setting the scene

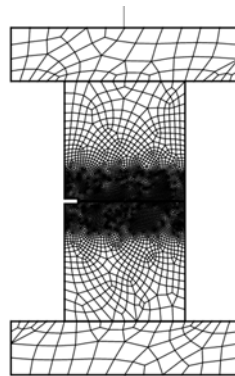
## Experimental world



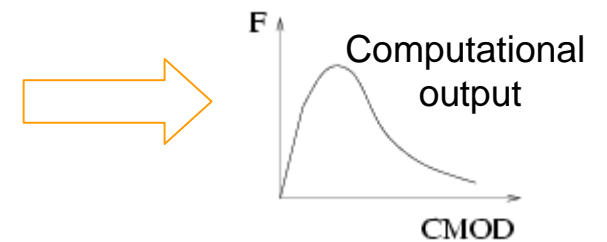
my PhD project



## Numerical world



mathematical equations  
containing parameters



# Project objectives

## □ Parameters identification of continuum damage models:

- **Study of the aspects related to the solution of the inverse problem:**
  - ✓ Uniqueness and robustness of the solution (well-posedness of the inverse problem)
  - ✓ Factors of influence for the solution (e.g. experimental uncertainty, initial guess)
  - ✓ Qualitative and quantitative choice of the experimental data
  
- **Study of the aspects related to the choice of the inverse technique (best strategy)**
  - ✓ Effectiveness (how close to the solution)
  - ✓ Efficiency (time)
  - ✓ Reliability

# Project objectives

## □ Insight in the calibrated numerical model:

- solving the inverse problem **needs** insight in the forward problem, otherwise it reduces to mere data fitting
- solving the inverse problem **helps** to have insight in the forward problem (e.g. **length scale**)
- Investigation of the limitations of applicability, reliability and predictive capabilities of the calibrated numerical model (**size effect and geometry effect**)

# Project objectives

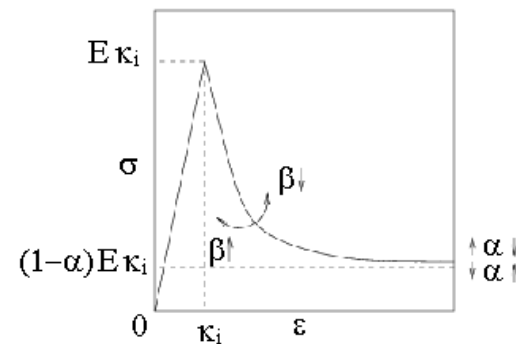
- ❑ **Study of the problem of objectively extracting intrinsic material properties from structural experimental responses:**
  - **Numerical model is an approximation of the reality**
    - ✓ many external factors that play a role in the laboratory tests are difficult to be identified, quantified and included in the model
    - ✓ acting only on the model parameters may not be sufficient to cover the approximation
    - ✓ consequence: not constant material parameters.
  - **Possible dependency of the material parameters from**
    - ✓ structural factors: the boundary conditions, the load conditions, the specimen size and geometry
    - ✓ environmental and manufacturing factors
    - ✓ time and/or deformation state
  - **Inverse problem only valid tool to link local law at the material point level with structural response**



# The numerical model (forward problem)

## Gradient-enhanced continuum damage model

$$\left\{ \begin{array}{l} \boldsymbol{\sigma} = (1 - \omega) \mathbf{D}^{\text{el}} \boldsymbol{\varepsilon} \\ \varepsilon_{\text{eq}} = \varepsilon_{\text{eq}}(\boldsymbol{\varepsilon}) \\ \omega = \omega(\kappa) \\ \kappa = \max(\kappa_i, \varepsilon_{\text{eq}}) \\ \left\{ \begin{array}{l} \bar{\varepsilon}_{\text{eq}} - c \nabla^2 \bar{\varepsilon}_{\text{eq}} = \varepsilon_{\text{eq}} \end{array} \right. \end{array} \right.$$



tensile-compressive strength ratio  $\eta$  gradient parameter (related to length scale)  $\alpha$

elastic parameters  $\mathbf{x}^T = [E, \nu, \kappa_i, \alpha, \beta, \eta, c]$  softening curve parameters

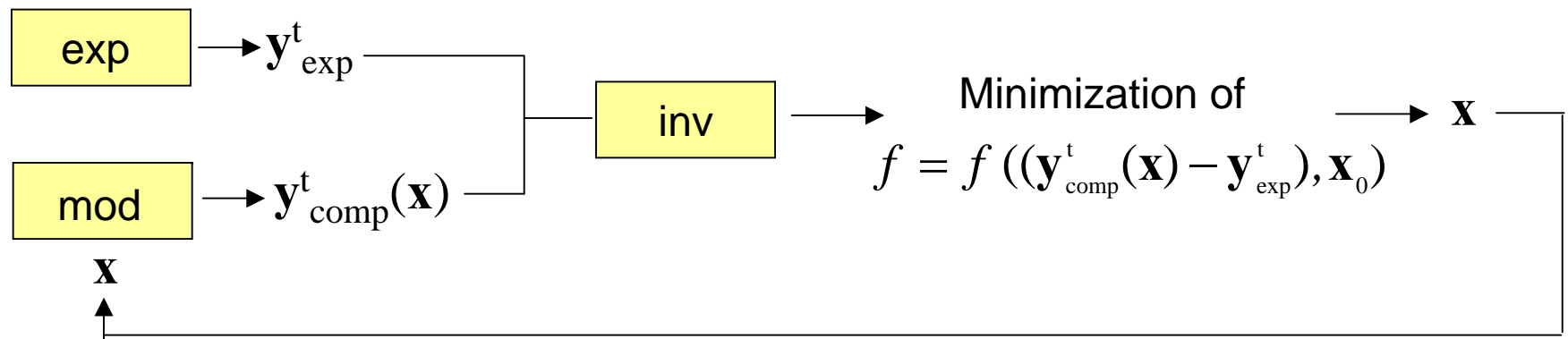
damage threshold  $\kappa_i$

**Simplification:**

$$\mathbf{x}^T = [\alpha, \beta, c]$$

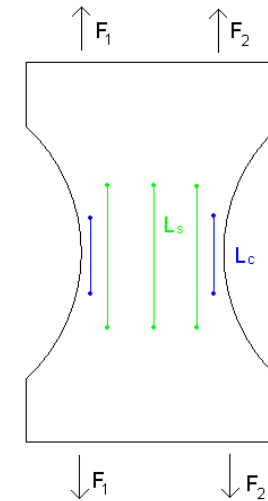
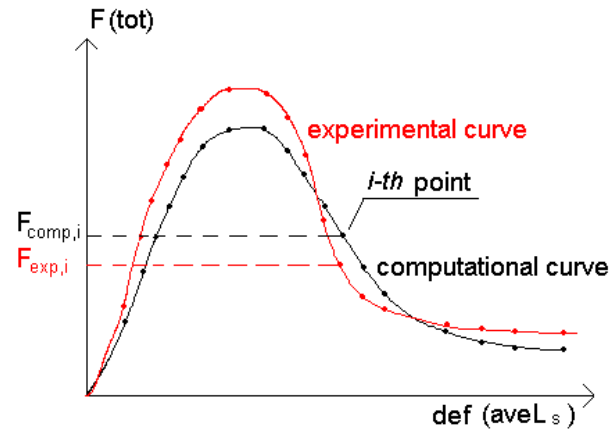
# The Inverse Problem

## Minimization of an objective function



# The Inverse Problem

## Definition of the objective function



$$\mathbf{y}_{\text{comp}}(\mathbf{x}) = [F_{\text{comp},1}(\mathbf{x}) \quad \dots \quad F_{\text{comp},i}(\mathbf{x}) \quad \dots \quad F_{\text{comp},N}(\mathbf{x})]^T$$

$$\mathbf{y}_{\text{exp}} = [F_{\text{exp},1} \quad \dots \quad F_{\text{exp},i} \quad \dots \quad F_{\text{exp},N}]^T$$

covariance

$$\mathbf{C}_{\text{exp}} = \begin{bmatrix} C_{\text{exp},1}^2 & 0 & 0 \\ 0 & C_{\text{exp},i}^2 & 0 \\ 0 & 0 & C_{\text{exp},N}^2 \end{bmatrix}$$

$$f(\mathbf{x}) = (\mathbf{y}_{\text{comp}}(\mathbf{x}) - \mathbf{y}_{\text{exp}})^T \cdot \mathbf{C}_{\text{exp}}^{-1} \cdot (\mathbf{y}_{\text{comp}}(\mathbf{x}) - \mathbf{y}_{\text{exp}}) = \sum_{i=1}^N \frac{1}{C_{\text{exp},i}^2} (F_{\text{comp},i}(\mathbf{x}) - F_{\text{exp},i})^2$$

weighted squared distance between exp and comp vectors

# The inverse techniques

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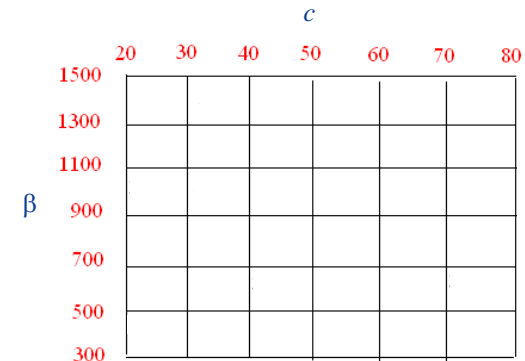
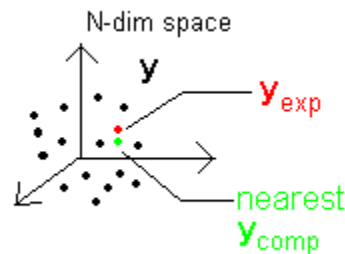
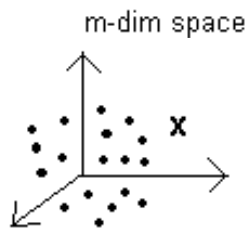
☐ KNN method

☐ Kalman filter method

# K-Nearest Neighbors method (KNN)

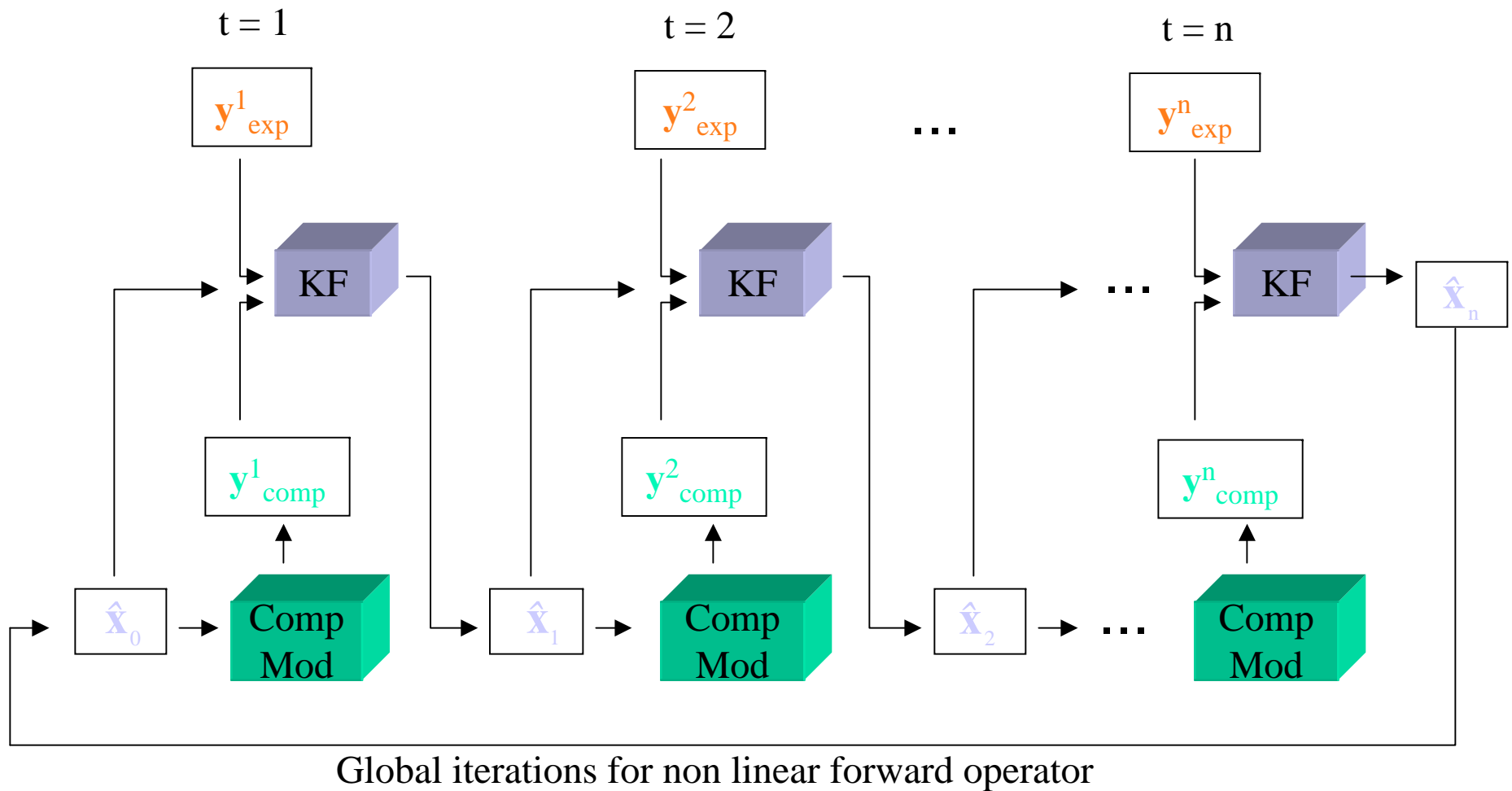
$$\hat{\mathbf{x}} = \min_{\mathbf{x}} f(\mathbf{x})$$

- ★ choose a population of model parameters sets  $\mathbf{x}_i$  (creation of a grid)
- ★ compute (forward problem)  $\mathbf{y}_{\text{comp}}(\mathbf{x}_i)$



- ★ evaluation of the weighted Euclidean distance  $f(\mathbf{x}_i)$
- ★ choose  $\mathbf{x}$  that corresponds to the nearest neighbor of  $\mathbf{y}_{\text{exp}}$  ( $K=1$ )

# Kalman Filter method (KF)



# The inverse techniques

## □ KNN method

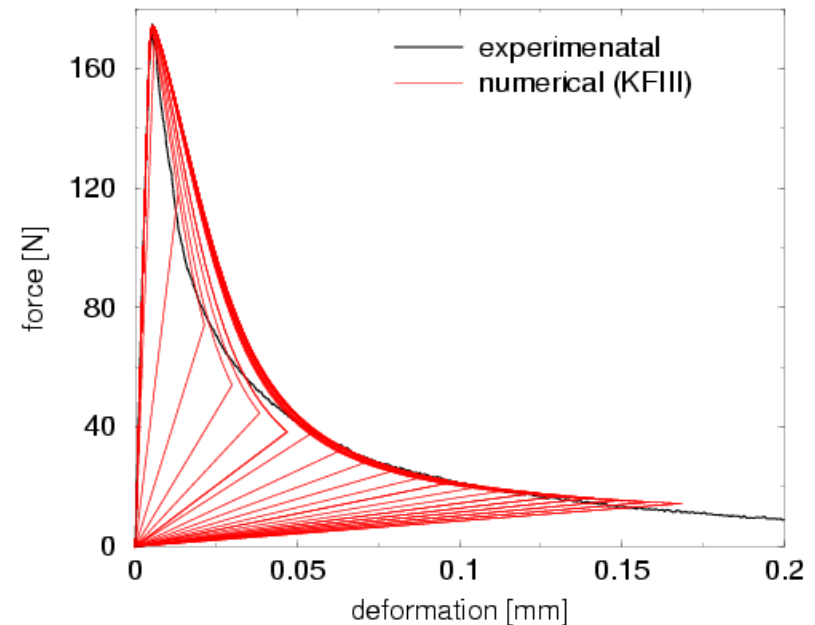
- ✓ Derivative free method
- ✓ General overview in the parameters space
- ✓ Estimation of the initial guess
- ✓ Parallel solutions of the forward problem
- ✓ easily usable for any numerical model (external tool)

## □ Kalman filter method

- ✓ Refine the searching process
- ✓ Parameters update during fracture process

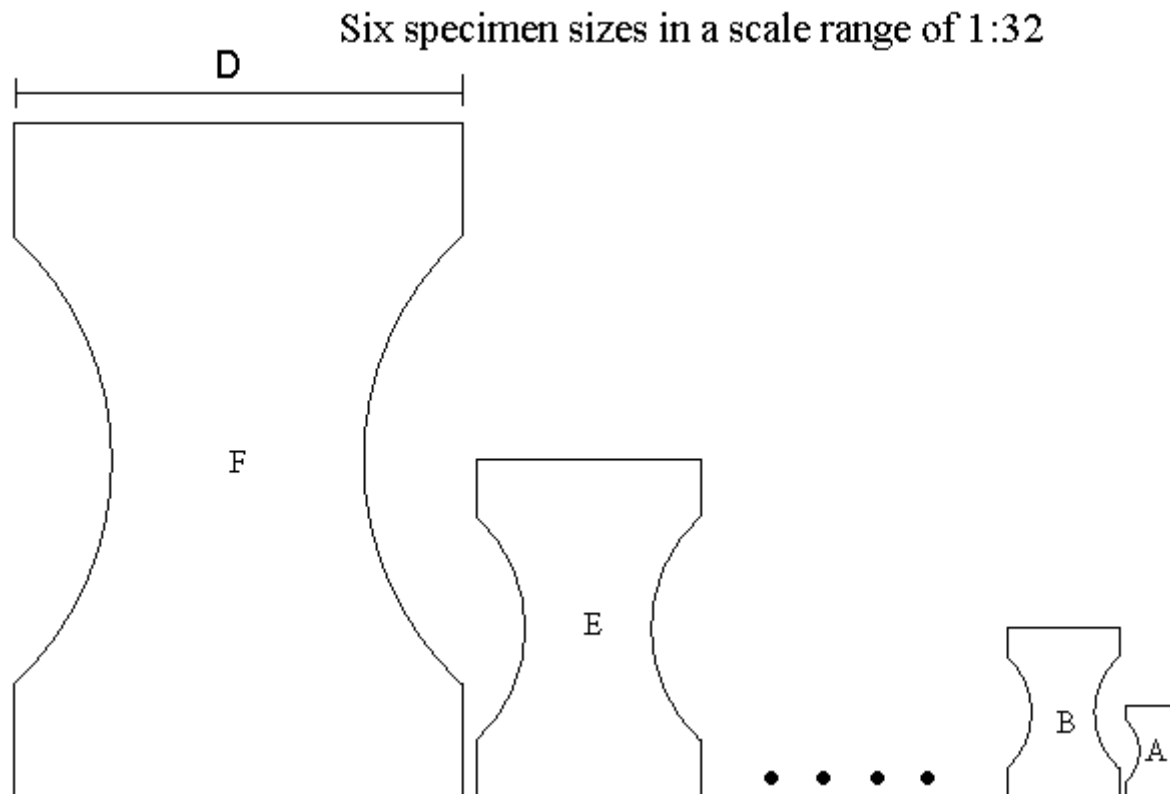
force–deformation diagram

Type B



# Experimental data 1

Tensile size effect tests on dog-bone shaped specimens by van Vliet and van Mier (2000)

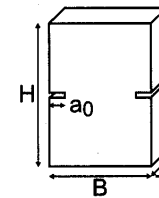
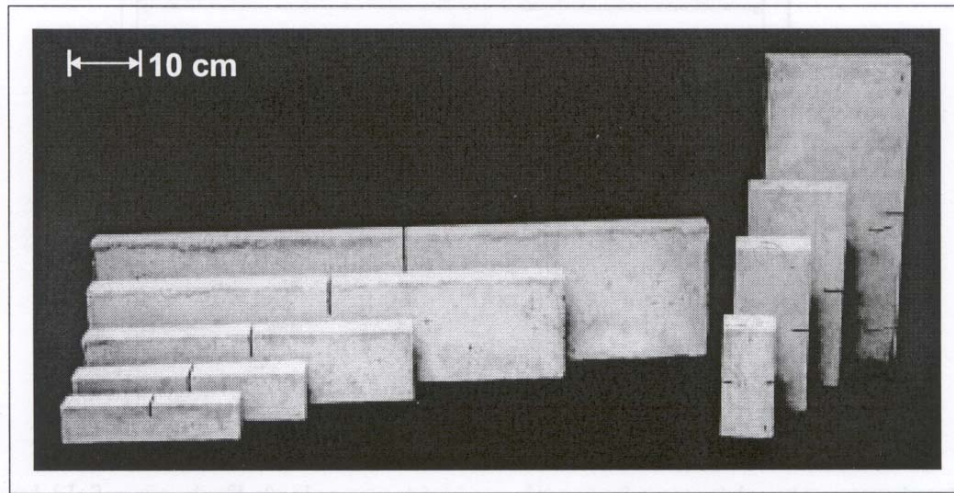




# Experimental data 2

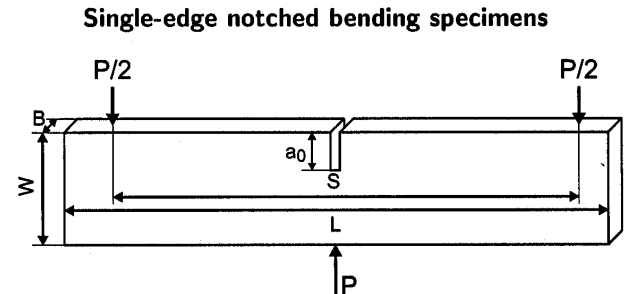
## Tensile Size Effect Tests (different concrete mixes) by K. Hariri (2000)

- Three point bending tests (BG) on single-edge-notched concrete beams
- Uniaxial tensile tests (KG) on double-notched concrete prisms



**Double-edge notched tensile specimens**

Size	Width $B$	Height $H$	Thickness $T$	Notch $a_0$
<b>KG 1</b>	80 mm	180 mm	80 mm	10 mm
<b>KG 2</b>	120 mm	270 mm	80 mm	15 mm
<b>KG 3</b>	160 mm	360 mm	80 mm	20 mm
<b>KG 4</b>	240 mm	540 mm	80 mm	30 mm

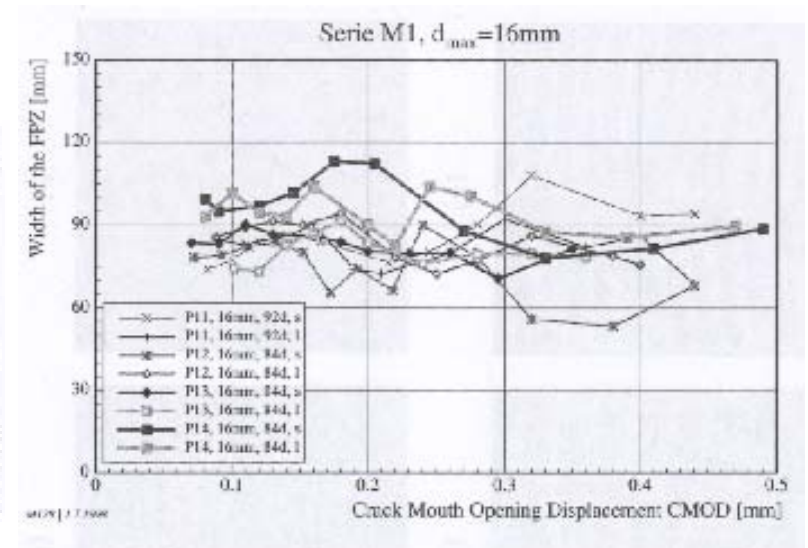
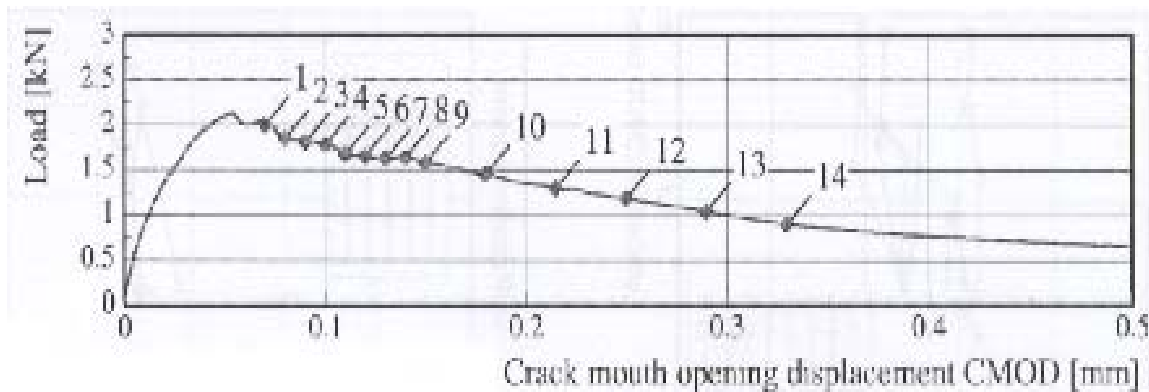


**Single-edge notched bending specimens**

Size	Thickness $B$	Height $W$	Length $L$	Span $S$	Notch $a_0$
<b>BG 1</b>	60 mm	60 mm	260 mm	240 mm	20 mm
<b>BG 2</b>	60 mm	80 mm	380 mm	320 mm	30 mm
<b>BG 3</b>	60 mm	120 mm	560 mm	480 mm	40 mm
<b>BG 4</b>	60 mm	180 mm	840 mm	720 mm	60 mm
<b>BG 5</b>	60 mm	240 mm	1120 mm	960 mm	80 mm

## Experimental data 2

□ Experimental available results:



□ Speckle Interferometry for the FPZ-size evaluation

# Objective of the fitting

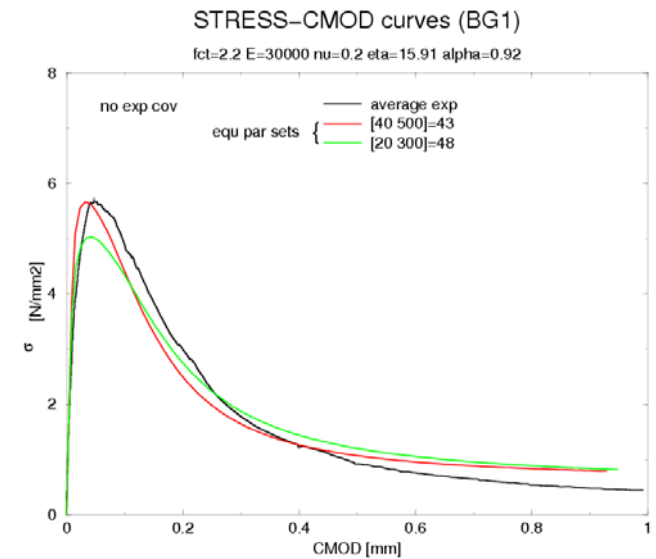
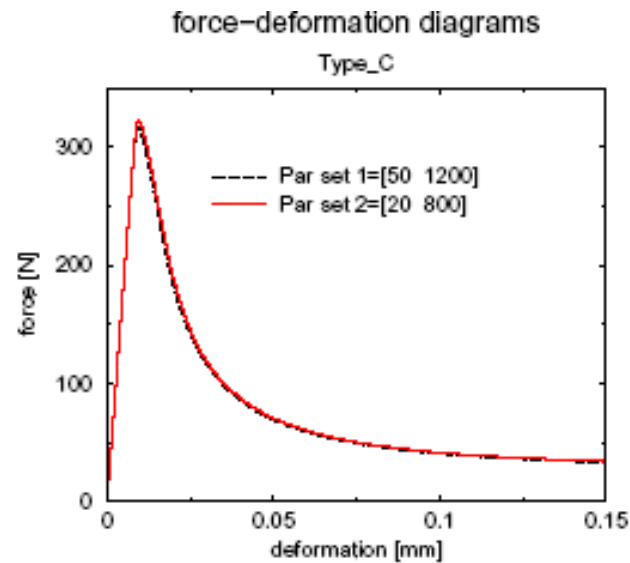
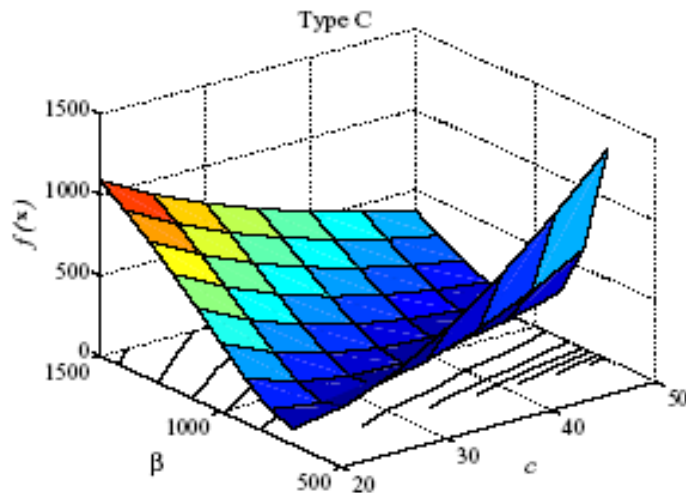
- ① Global curve one single size
- ② Global + local curve one single size
- ③ Size effect curve (only peaks)
- ④ Global curves different sizes
- ⑤ Global + local curves different sizes
- ⑥ Global + local curves different sizes and geometry

# Results

## ① Global curve one single size

✓ Ill-posed inverse problem:

- ♦ not unique parameters set
- ♦  $c$  and  $\beta$  correlated

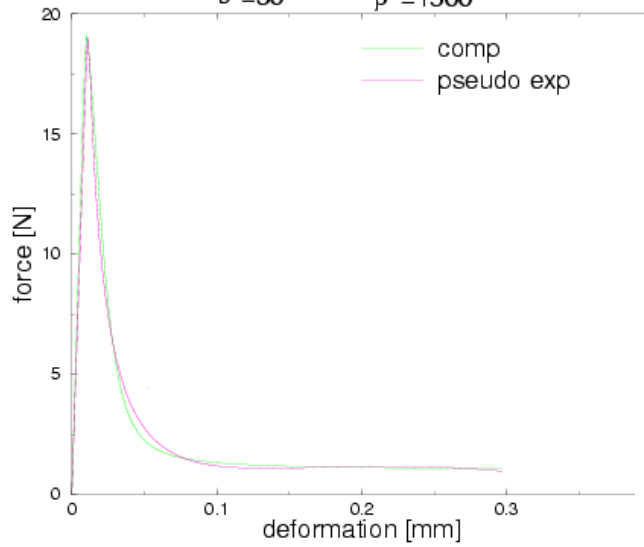


# Results

## ② Global + local curve one single size

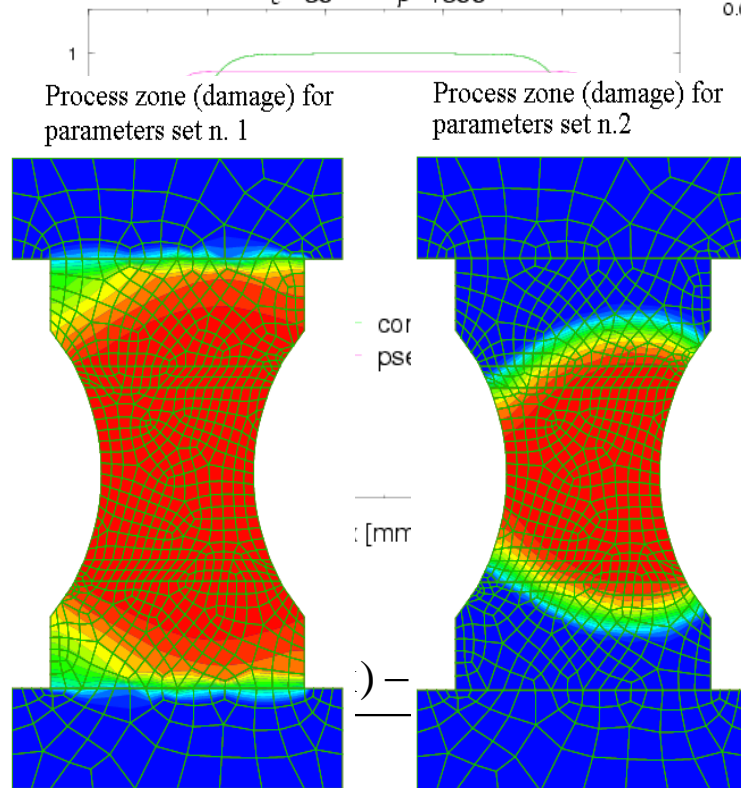
force-deformation diagram

$c = 30$   $\beta = 1500$



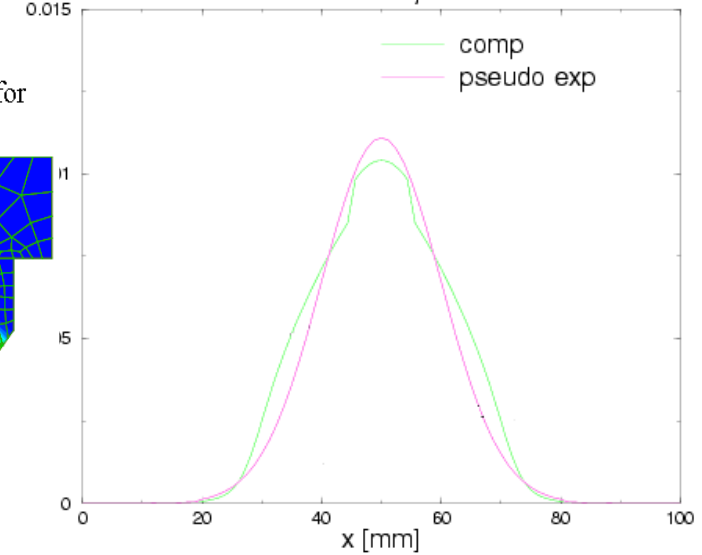
Damage profile

$c = 30$   $\beta = 1500$



Equivalent strain profile (local)

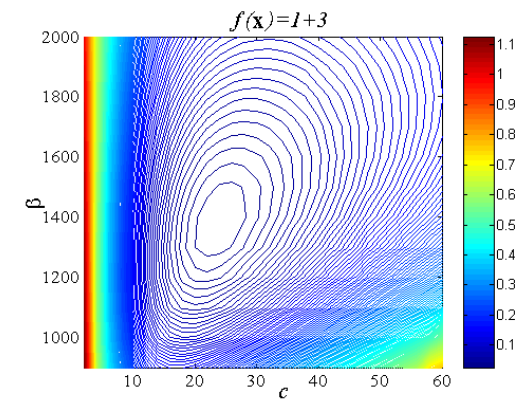
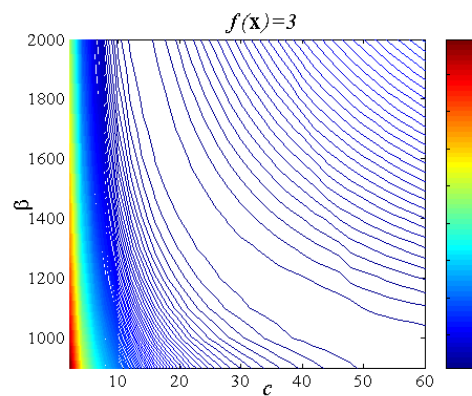
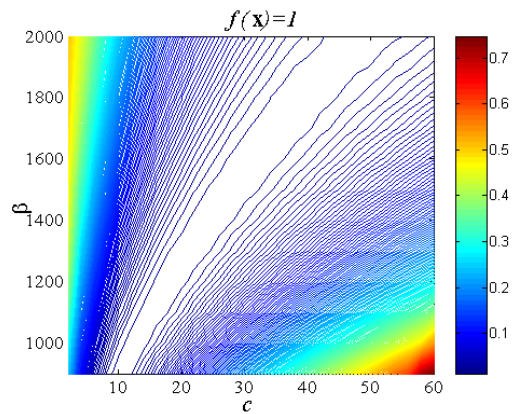
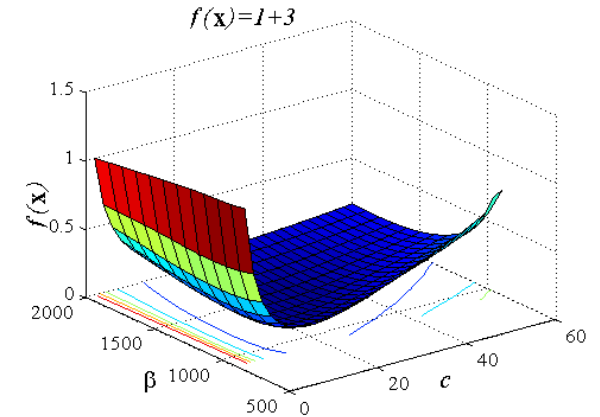
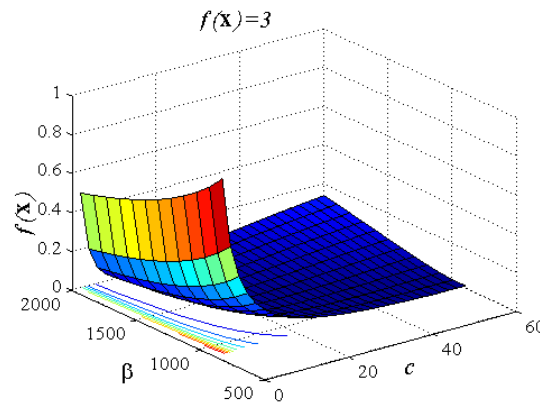
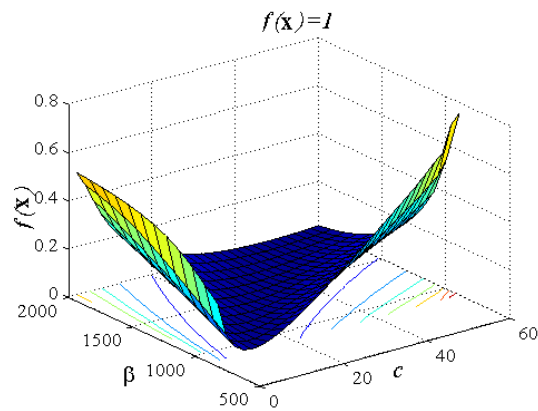
$c = 30$   $\beta = 1500$



$$f(\mathbf{x}) = \underbrace{\frac{(\mathbf{F}_{\text{comp}}(\mathbf{x}) - \mathbf{F}_{\text{exp}})^T (\mathbf{F}_{\text{comp}}(\mathbf{x}) - \mathbf{F}_{\text{exp}})}{\mathbf{F}_{\text{exp}}^T \mathbf{F}_{\text{exp}}}}_1 + \underbrace{\frac{(\boldsymbol{\varepsilon}_{\text{comp}}(\mathbf{x}) - \boldsymbol{\varepsilon}_{\text{exp}})^T (\boldsymbol{\varepsilon}_{\text{comp}}(\mathbf{x}) - \boldsymbol{\varepsilon}_{\text{exp}})}{\boldsymbol{\varepsilon}_{\text{exp}}^T \boldsymbol{\varepsilon}_{\text{exp}}}}_3 + \underbrace{\frac{\omega_{\text{exp}}}{\omega_{\text{exp}}}}_2$$

# Results

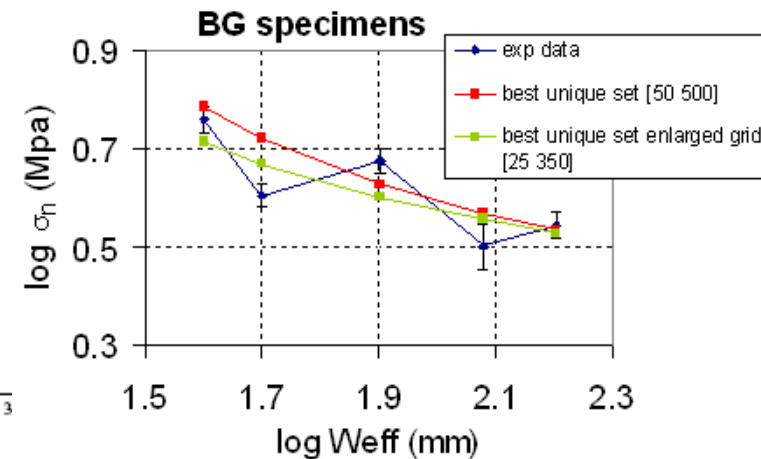
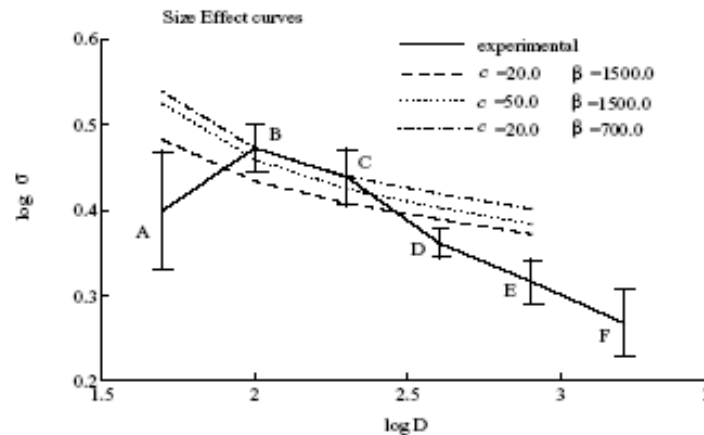
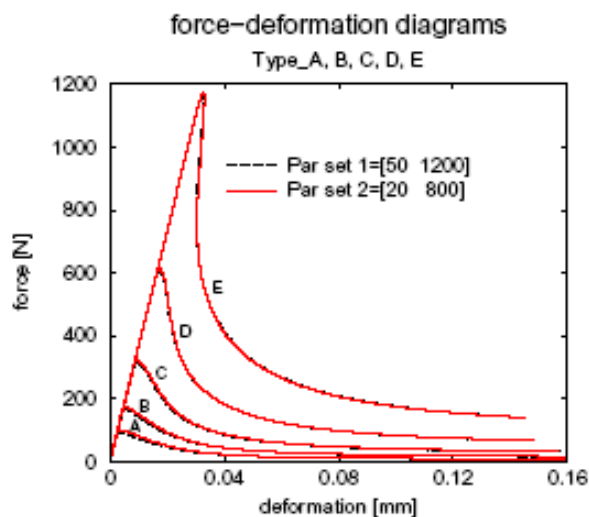
- ✓ Single parameters set identified
- ✓ Fitting of other sizes curves not guaranteed



# Results

## ③ Size effect curve (only peaks)

- ✓ Different parameter sets could give “good” average fitting
- ✓ Fitting of the entire global curves not guaranteed
- ✓ No unique parameters set reproduces the real size effect curve (statistical effects not captured by the deterministic model)
- ✓ The length scale may be used as tuner parameter.

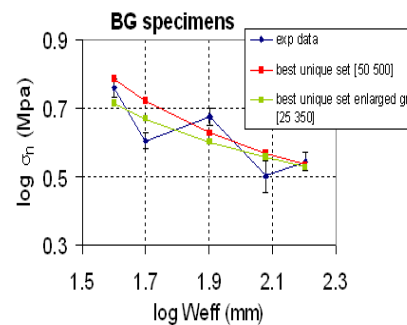
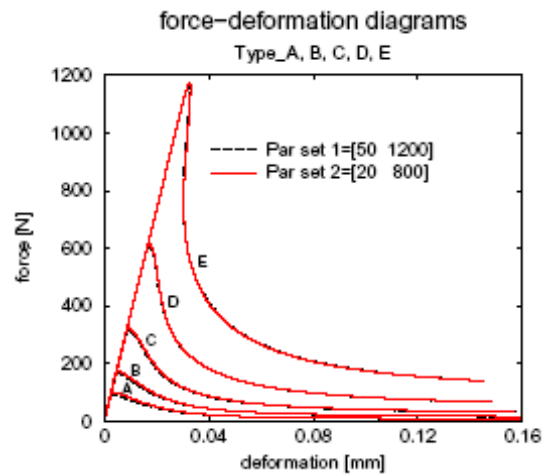




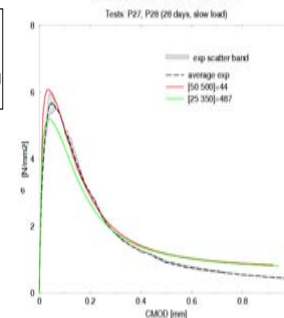
# Results

## ④ Global curves different sizes

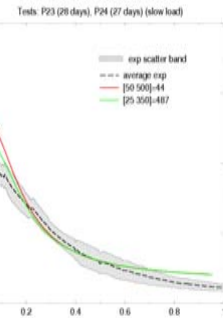
- ✓ Different parameter sets could give “good” average fitting.
- ✓ No unique parameters set reproduces the real size effect curve
- ✓ The length scale may be used as tuner parameter.



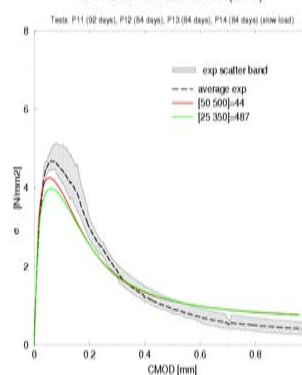
STRESS-CMOD curves BG1



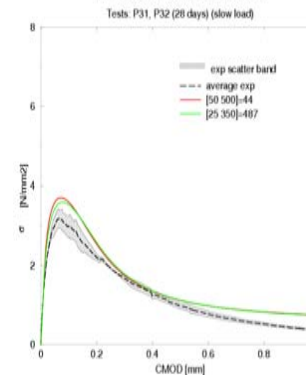
STRESS-CMOD curves BG2



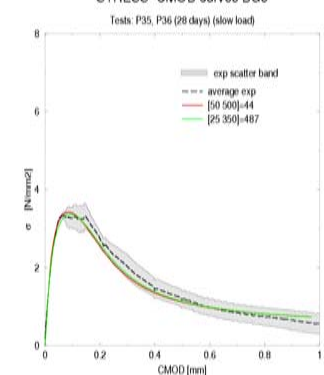
STRESS-CMOD curves (BG3)



STRESS-CMOD curves BG4



STRESS-CMOD curves BG5

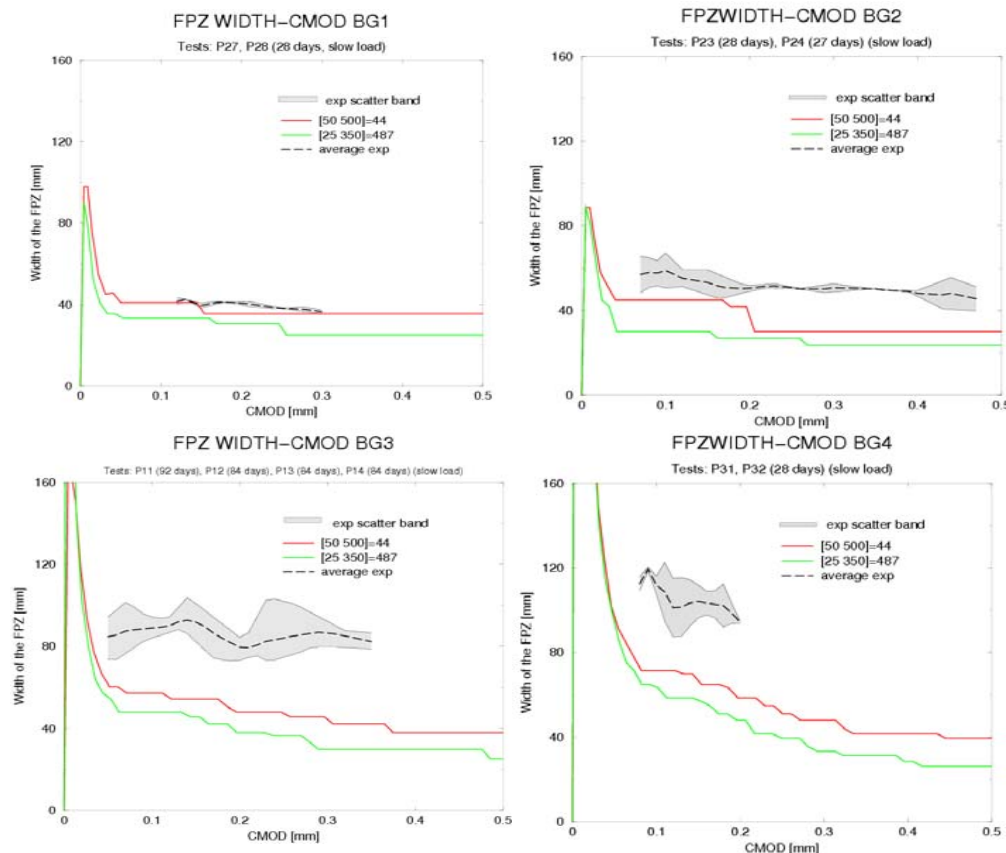




# Results

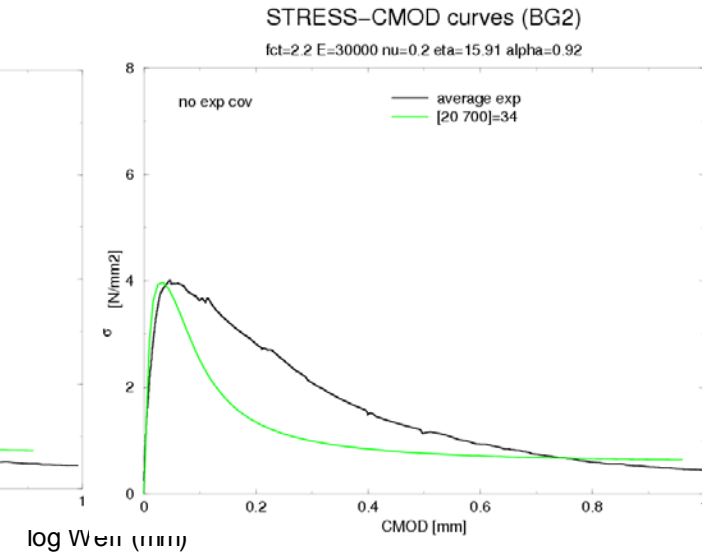
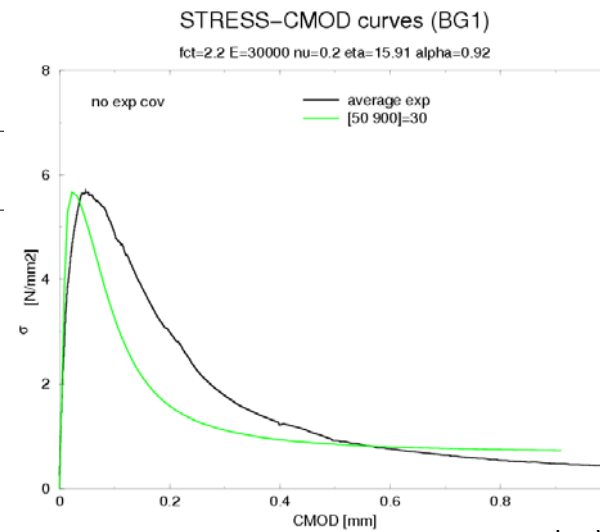
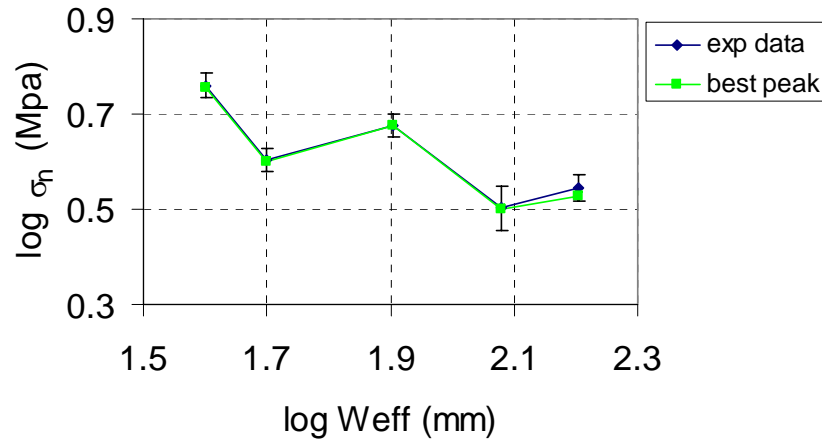
## Global + local curves different sizes

- ✓ Single parameters set may be identified.
- ✓ No unique parameters set reproduces the real size effect curve.
- ✓ The length scale may be used as tuner parameter.



# Results: no unique parameters set reproduces the real size effect curve.

## BG specimens



## KNN results (c and beta minimum)

FPZ width computed using the non loc equ strain profile with a threshold of 20% of the peak (no exp cov)

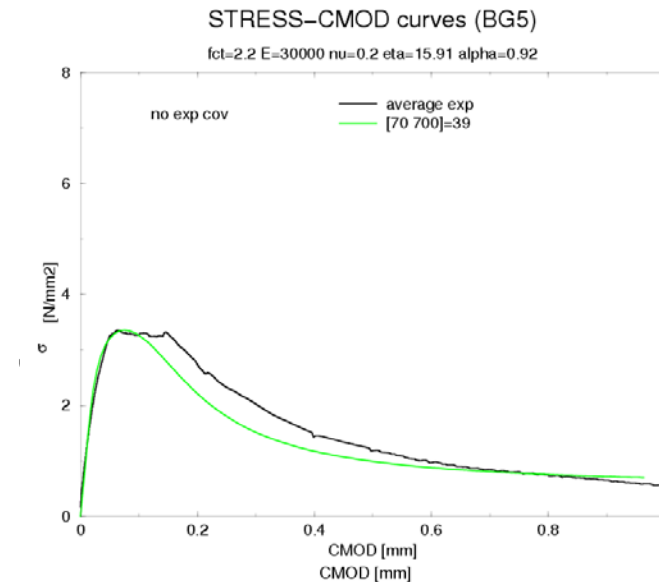
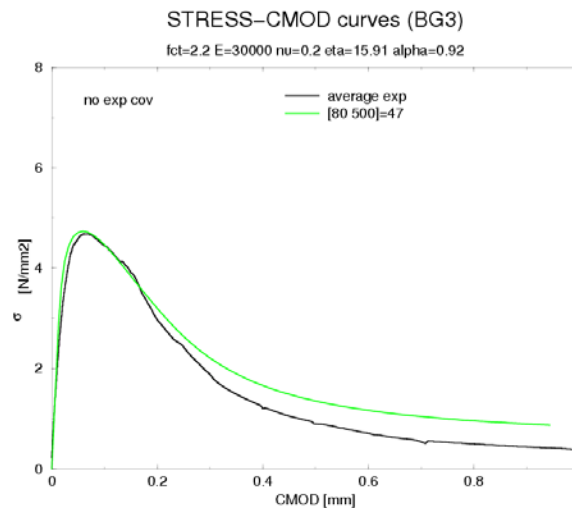
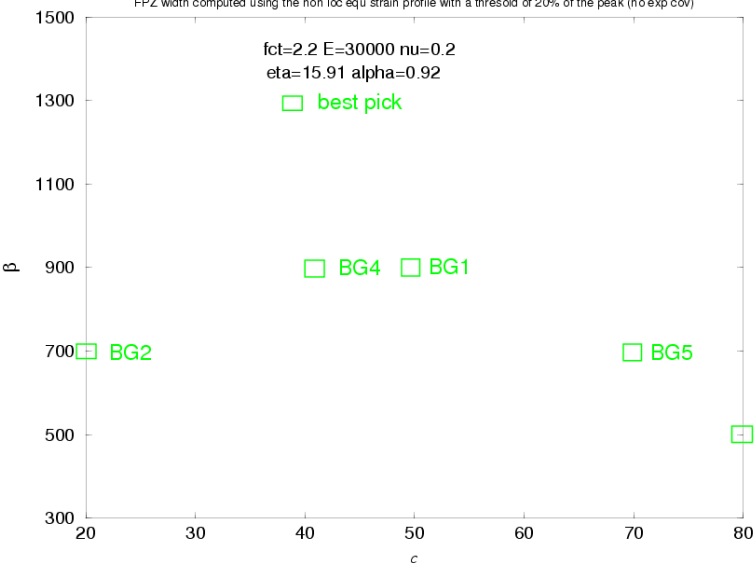
$fct=2.2$ ,  $E=30000$ ,  $\nu=0.2$ ,  $\eta=15.91$ ,  $\alpha=0.92$

best pick

BG4 BG1

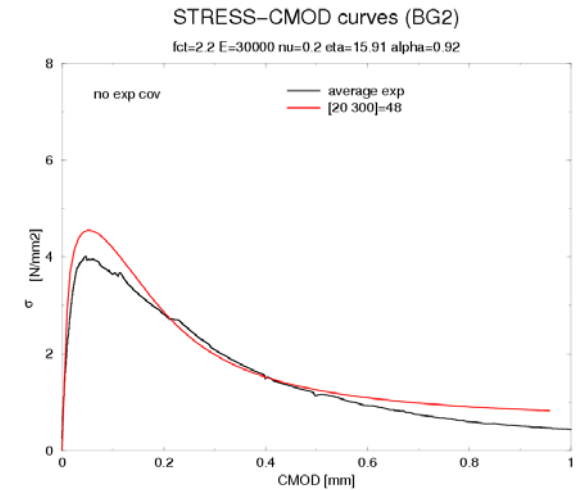
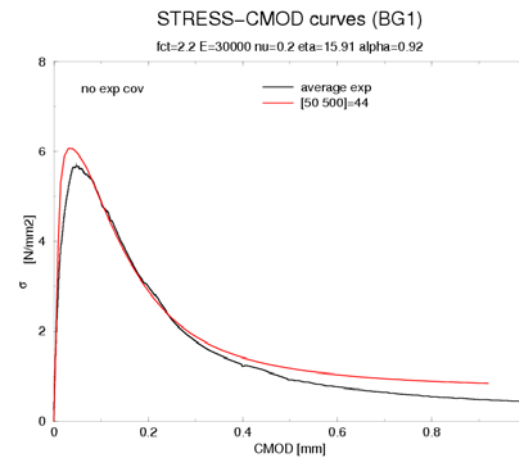
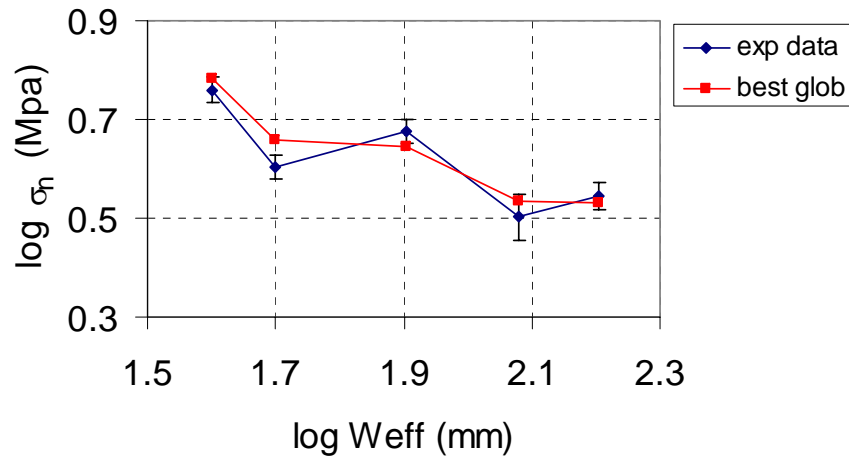
BG5

BG3

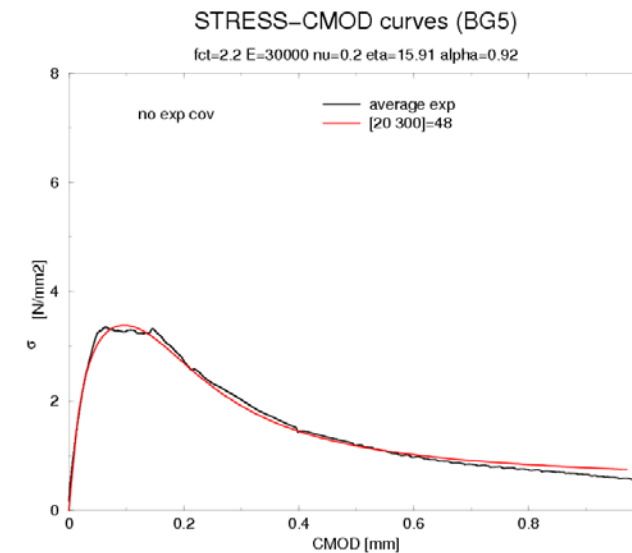
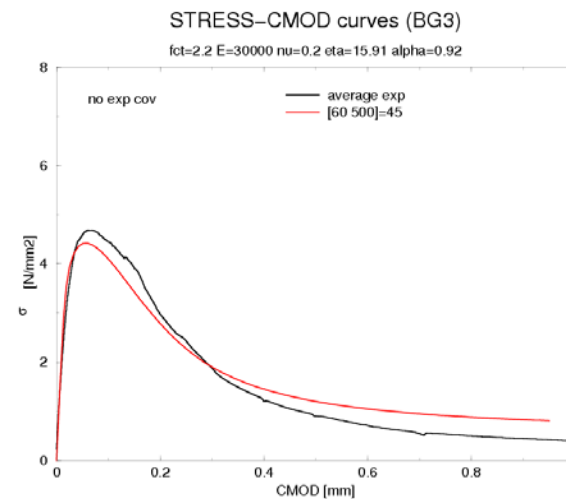
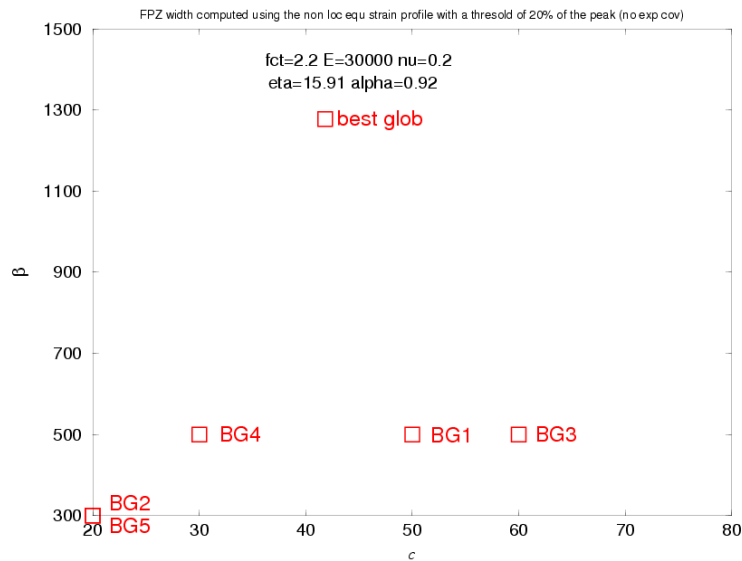


# Results: fitting only the peaks $\neq$ fitting the entire global curves

## BG specimens

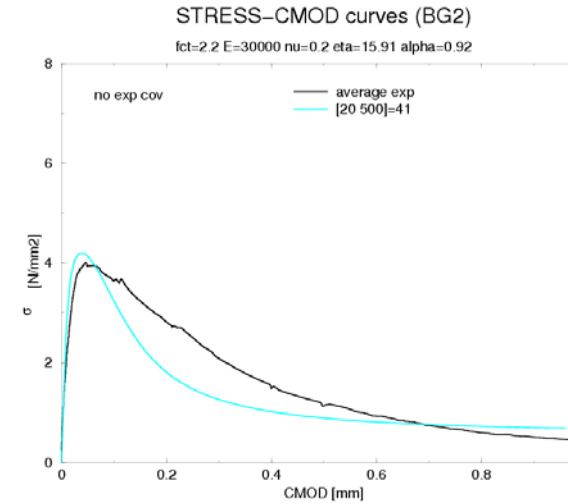
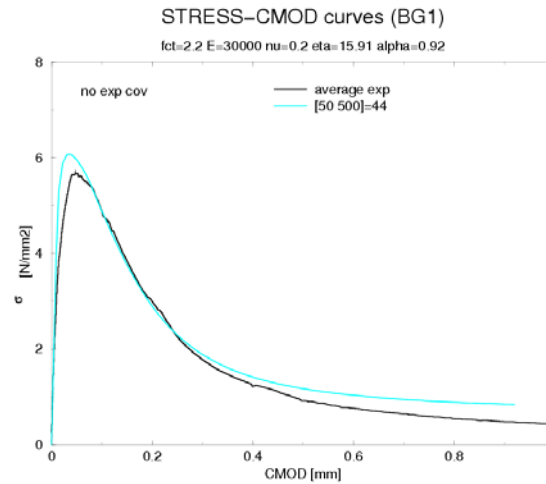
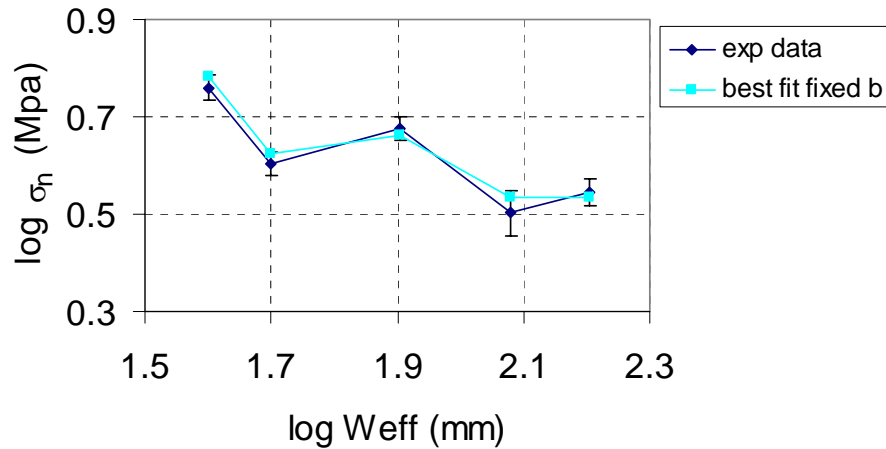


## KNN results (c and beta minimum)

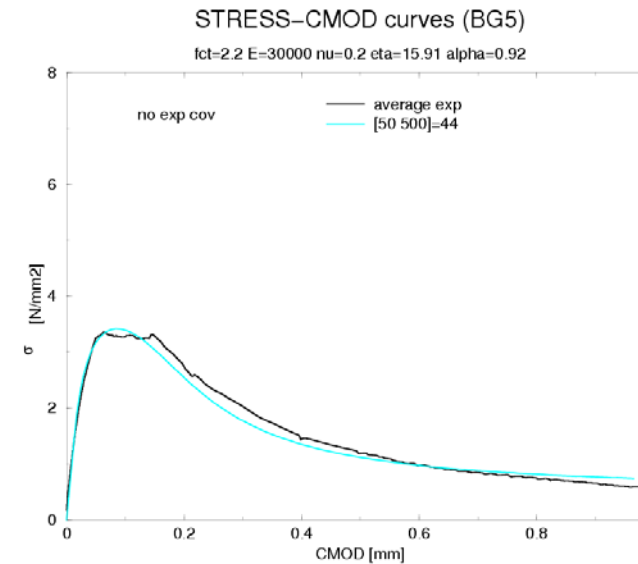
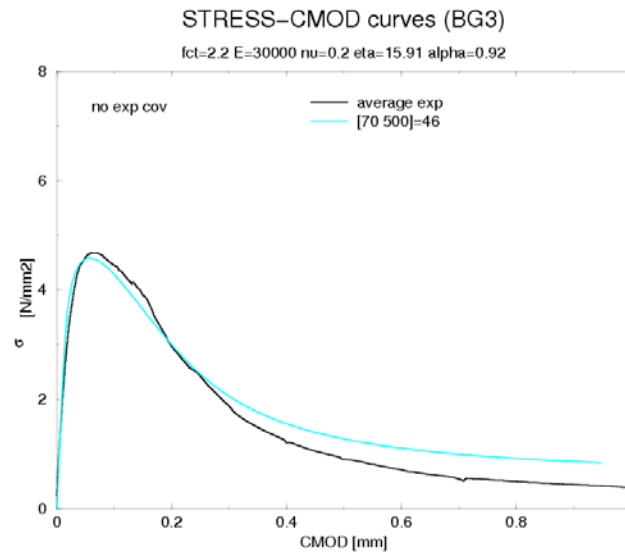
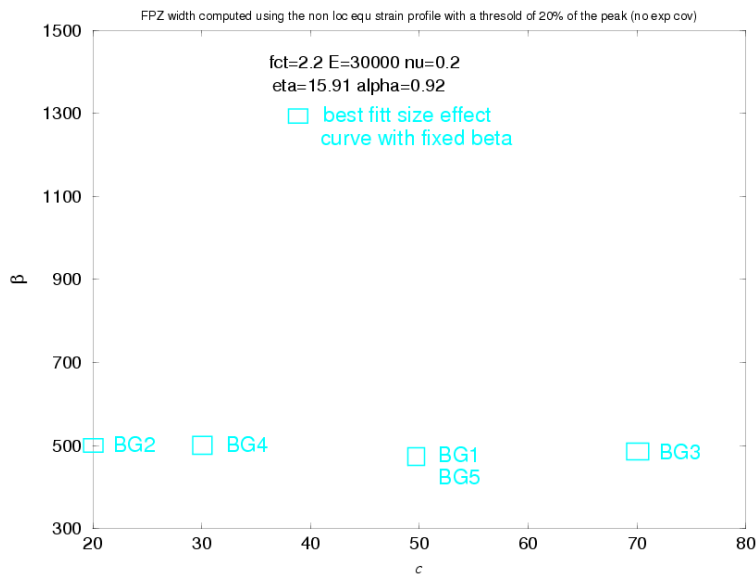


# Results: the length scale may be used as tuner parameter

## BG specimens



## KNN results (c and beta minimum)

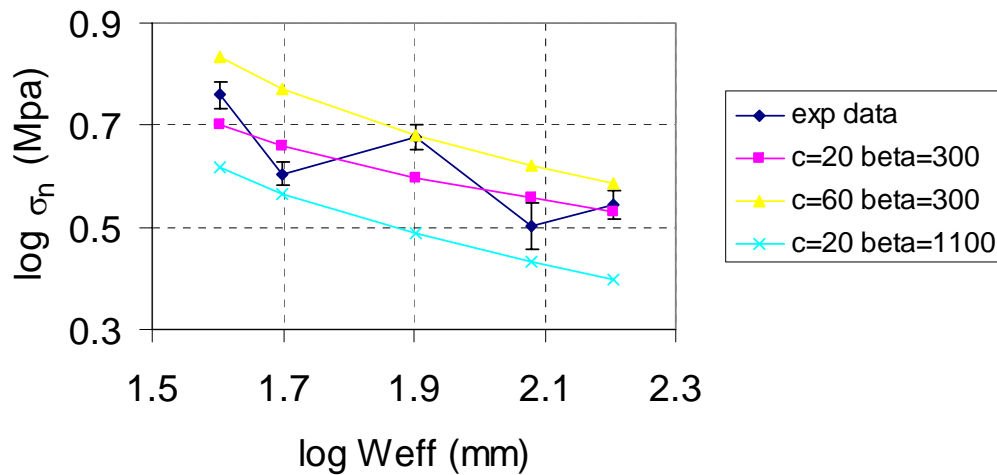


# Results

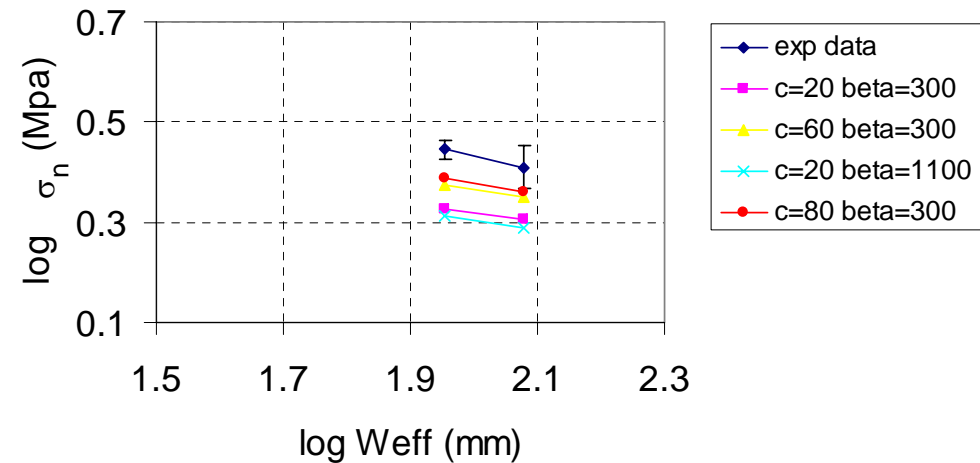
## ↩ Global + local curves different sizes and geometry

✓ Structural effect

**BG specimens**



**KG specimens**

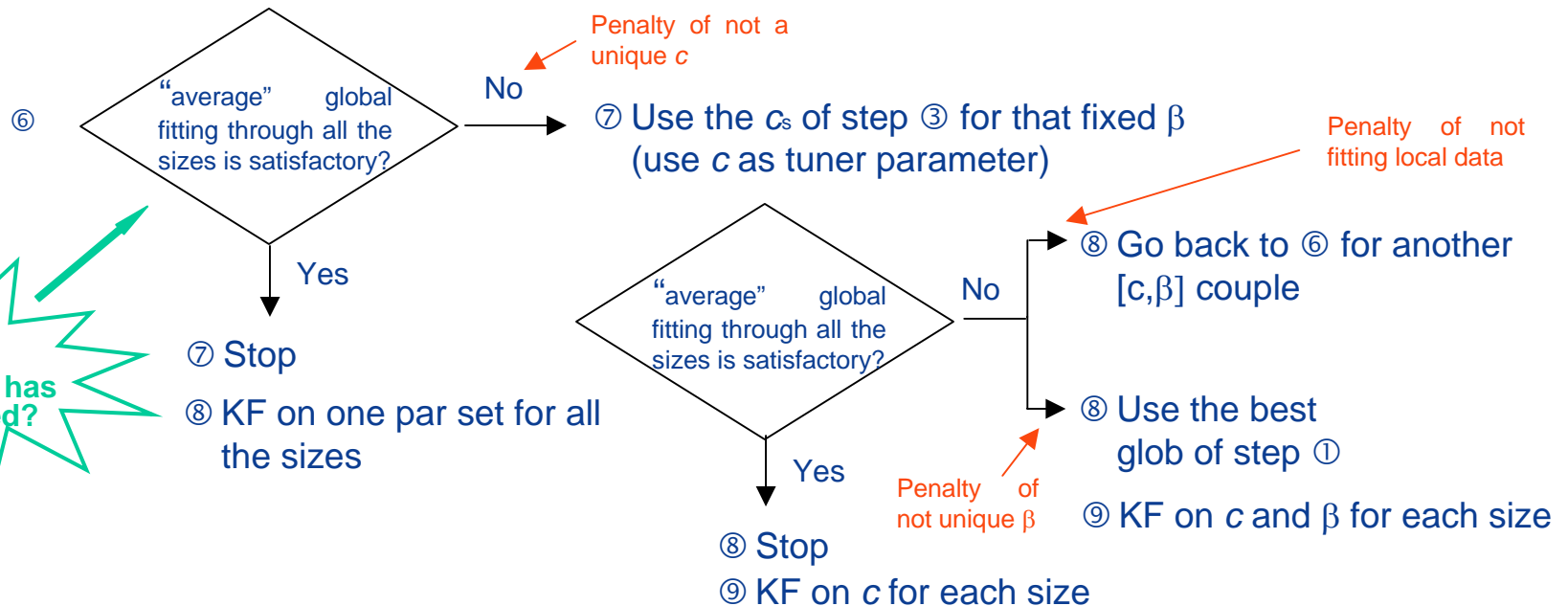
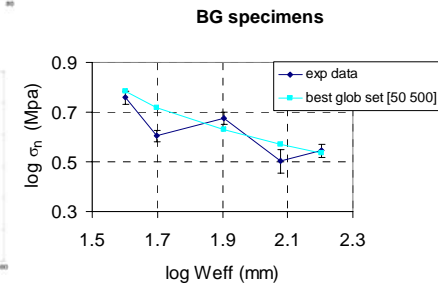
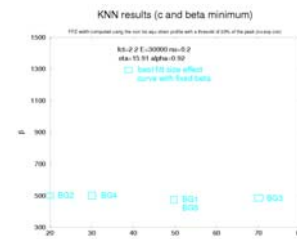
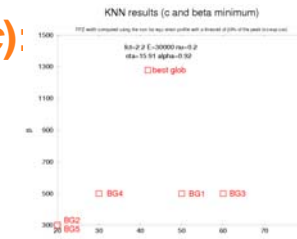


# Conclusions (parameters identification strategy)

## Parameters identification procedure (for $\beta$ and $c$ ):

- ① KNN method to identify the best glob for each size.
- ② Find the better fixed  $\beta_s$  (better representatives of the “best glob” population)
- ③ Find for each better  $\beta$  the best  $c$  for each size.  
(peaks below the computational curve of a fixed  $[\beta, c]$  couple have smaller  $c$  and vice versa)
- ④ Find the best fixed  $c$  for each better  $\beta$  (the best representative of each “fixed  $\beta$ ” population)
- ⑤ Find the best  $[c, \beta]$  set considering the local curves (priority of fitting to the glob curves)

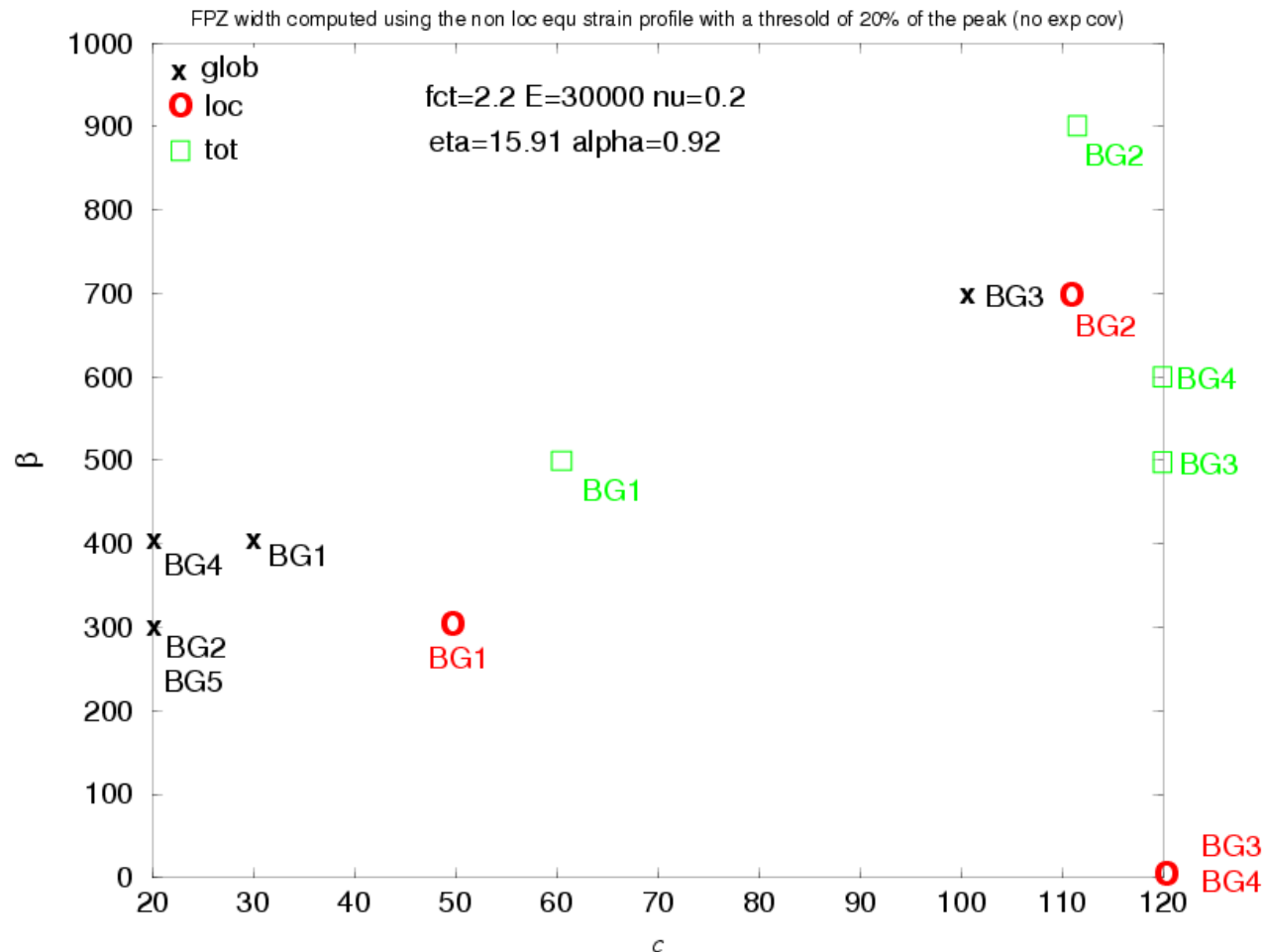
Simply looking  
in the KNN  
matrix



How the  
objective has  
to be fitted?

# Conclusions (Hariri tests: global overview)

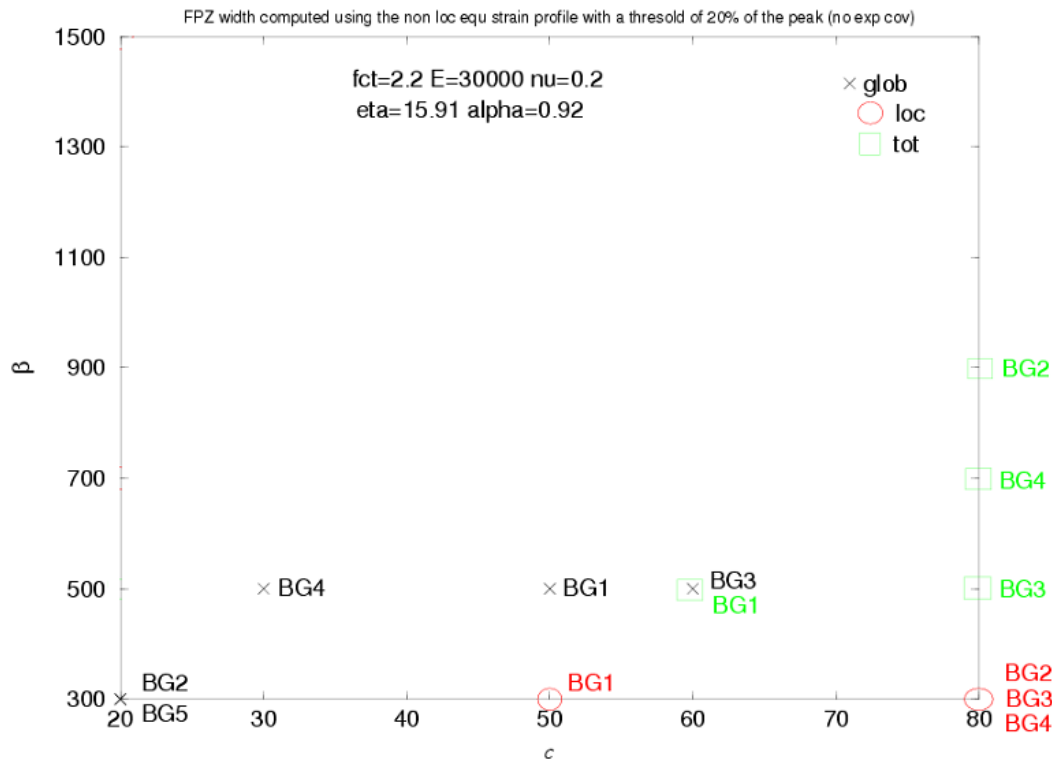
## KNN results (c and beta minimum)



- Average fitting of the **global size effect** obtained by one single set with  $c$  toward the smallest value.
- Detailed fitting of the **global size effect** varying  $c$
- Spread of the parameters sets to obtain the best fitting of the **local size effect**.
- Best individuals at borders!!!
- Structural effect on the model parameters.
- May parameters identification, solved as inverse problem, completely substitute investigation at micro or meso-scale?

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### KNN results (c and beta minimum)



### KNN results (c and beta minimum)

